

Dynamic Discrete Choice Models

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Example: Fertility Decision

Per period utility

Having a child: $uX - C + \epsilon_1$

Not having a child: $uX + \epsilon_2$

X_t : Number of children: state vector

u : utility parameter of having a child

c : cost of having a child.

Next period state variable

Have a child: $X_{t+1} = X_t + 1$

Not have a child: $X_{t+1} = X_t$

Final period

Utility function:

$$V_T(X_T) = uX_T$$

Final period expected utility function:

$$E_{T-1}[V_T(X_T)] = uX_T$$

Calculate $V_T(X_T)$ for each $X_T = 0, \dots, 20$ Calculate
 $E_{T-1}[V_T(X_T)]$ for each $X_T = 0, \dots, 20$

Period $T - 1$

- ▶ Value of having a child:

$$V_{CT-1}(X_{T-1}, \epsilon_{T-1}) = uX_{T-1} - c + \beta EV(X_T) + \epsilon_{1T-1}$$

where

$$X_T = X_{T-1} + 1$$

- ▶ value of not having a child:

$$V_{NT-1}(X_{T-1}, \epsilon_{T-1}) = uX_{T-1} + \beta EV(X_T) + \epsilon_{2T-1}$$

where

$$X_T = X_{T-1}$$

Then, the value function at period $T - 1$ is

$$V_{T-1}(X_{T-1}, \epsilon_{T-1}) = \text{Max} \{V_{CT-1}(X_{T-1}, \epsilon_{T-1}), V_{NT-1}(X_{T-1}, \epsilon_{T-1})\}$$

Derive the expected value function $EV_{T-2}(X_{T-1}, \epsilon_{T-1})$

By simulation:

- ▶ Given the distribution of ϵ , draw ϵ_{T-1}^m .
- ▶ Calculate $V_{T-1}(X_{T-1}, \epsilon_{T-1}^m)$, $m = 1, \dots, M$
- ▶ $\hat{E}V_{T-1}(X_{T-1}, \epsilon_{T-1}) \approx \frac{1}{M} \sum_{m=1}^M V_{T-1}(X_{T-1}, \epsilon_{T-1}^m)$
- ▶ Calculate the above expected value function for $X_{T-1} = 0, \dots, 20$

Repeat the above algorithm from $T - 1$ to 1.

After the dynamic Programming algorithm, we know

$$EV(X_T), EV(X_{T-1}, \epsilon_{T-1}), \dots, EV(X_1, \epsilon_1)$$

. for all $X_t = 0, \dots, 20$.

Simulated Likelihood Calculation

Simulate choice probability for an individual at age t who has X_t children, and decided to have one more child.

- 1 Draw $\epsilon_{1t}^m, \epsilon_{2t}^m$
- 2 Derive the value function.

$$V_{Ct}(X_t, \epsilon_t^m) = uX_t - c + \beta EV(X_{t+1}, \epsilon_{t+1}) + \epsilon_{1t}^m$$

where $X_{t+1} = X_t + 1$

$$V_{Nt}(X_t, \epsilon_t^m) = uX_t + \beta EV(X_{t+1}, \epsilon_{t+1}) + \epsilon_{2t}^m$$

where $X_{t+1} = X_t$

- 3 if $V_{Ct}(X_t, \epsilon_t^m) \geq V_{Nt}(X_t, \epsilon_t^m)$ then $I_C(X_t, \epsilon_t^m) = 1$,
i.e. decides to have a child.
Otherwise $I_C(X_t, \epsilon_t^m) = 0$, i.e. decides not to have a
child.

Repeat 1-3 for $m = 1, \dots, M$ and calculate the simulated choice
probability.

$$\hat{P}_{Ct}(X_t) = \frac{1}{M} \sum_{m=1}^M I_C(X_t, \epsilon_t^m)$$

If the person actually chose to have the child, then

log likelihood increment: $\ln \left[\hat{P}_{Ct}(X_t^d) \right]$ If she did not, then

log likelihood increment: $\ln \left[1 - \hat{P}_{Ct}(X_t^d) \right]$

The Computational Burden

- ▶ Integration over the taste shock has to be carried out at the Dynamic Programming stage of the estimation, as well as the likelihood calculation.
- ▶ Integrations at the DP stage has to be carried out at every possible state space point.

Rust, Econometrica (1987)

Denote the deterministic values of each choice as follows

$$\bar{V}_{Ct}(X_t) = uX_t - c + \beta EV(X_{t+1}, \epsilon_{t+1})$$

$$\bar{V}_{Nt}(X_t) = uX_t + \beta EV(X_{t+1}, \epsilon_{t+1})$$

Then,

$$V_{Ct}(X_t, \epsilon_t) = \bar{V}_{Ct}(X_t) + \epsilon_{Ct}$$

$$V_{Nt}(X_t, \epsilon_t) = \bar{V}_{Nt}(X_t) + \epsilon_{Nt}$$

and

$$V(X_t, \epsilon_t) = \text{Max} \{V_{Ct}(X_t, \epsilon_t), V_{Nt}(X_t, \epsilon_t)\}$$

If $\epsilon_{Ct}, \epsilon_{Nt}$ are i.i.d. extreme value distributed, then the expected value function (Emax function) is

$$EV(X_t, \epsilon_t) = \ln [\exp(\bar{V}_{Ct}(X_t)) + \exp(\bar{V}_{Nt}(X_t))]$$

and the fertility choice probability can be expressed as a logit:

$$P_{Ct}(X_t) = \frac{\exp(\bar{V}_{Ct}(X_t))}{\exp(\bar{V}_{Ct}(X_t)) + \exp(\bar{V}_{Nt}(X_t))}$$

Unobserved Heterogeneity

Heckman and Singer (1984)

- ▶ High fertility type: low c : c_H
- ▶ Low fertility type: high c : c_L
- ▶ Solve the DP problem for each fertility type.
- ▶ Get $EV_t(X_t, u, c_H)$, $EV_t(X_t, u, c_L)$

The likelihood increment for person i is:

$$\begin{aligned}
 & \pi I_{Hi} + (1 - \pi) I_{Li} \\
 = & \pi \prod_{t=t_1}^T \left\{ \left[\frac{\exp(\bar{V}_{Ct}(X_{it}, u, C_H))}{\exp(\bar{V}_{Ct}(X_{it}, u, C_H)) + \exp(\bar{V}_{Nt}(X_{it}, u, C_H))} \right]^{I_c} \right. \\
 & \left. + \left[\frac{\exp(\bar{V}_{Nt}(X_{it}, u, C_H))}{\exp(\bar{V}_{Ct}(X_{it}, u, C_H)) + \exp(\bar{V}_{Nt}(X_{it}, u, C_H))} \right]^{1-I_c} \right\} \\
 & + (1 - \pi) \prod_{t=t_1}^T \left\{ \left[\frac{\exp(\bar{V}_{Ct}(X_{it}, u, C_L))}{\exp(\bar{V}_{Ct}(X_{it}, u, C_L)) + \exp(\bar{V}_{Nt}(X_{it}, u, C_L))} \right]^{I_c} \right. \\
 & \left. + \left[\frac{\exp(\bar{V}_{Nt}(X_{it}, u, C_L))}{\exp(\bar{V}_{Ct}(X_{it}, u, C_L)) + \exp(\bar{V}_{Nt}(X_{it}, u, C_L))} \right]^{1-I_c} \right\}
 \end{aligned}$$

Parameter to be estimated: u, C_L, C_H, π .

- ▶ Suppose the data is divided into women who have many children and who do not.
- ▶ Then, for the first type, I_H is low and I_L is high. But the estimated weighted sum $\pi I_{Hi} + (1 - \pi) I_{Li}$ is higher than the estimated likelihood without heterogeneity I_i .
- ▶ For the second type, I_H is high and I_L is low. But the estimated weighted sum is higher than the likelihood without heterogeneity. I_i
- ▶ Because if there is no heterogeneity, the model predicts that women have neither many nor no children, which is not seen in the data.

Simulation

- ▶ Draw the unobserved type. Draw uniform distribution $\epsilon \sim U(0, 1)$.
 $c = c_H$ if $\epsilon \leq \pi$. $c = c_L$ otherwise.
- ▶ Start with $X_{t_1} = 0$. Draw uniform distribution $\epsilon \sim U(0, 1)$
- ▶ $X_{t_1+1} = X_{t_1} + 1$ if $\epsilon \leq P_{C_t}(X_t)$ $X_{t_1+1} = X_{t_1}$ if otherwise.
- ▶ Repeatedly simulate X_t for $t = t_1 + 1, \dots, T$