## ECON 351\* -- NOTE 11

# <u>The Multiple Classical Linear Regression Model (CLRM):</u> <u>Specification and Assumptions</u>

# **1. Introduction**

**CLRM** stands for the <u>Classical Linear Regression Model</u>. The CLRM is also known as the *standard* linear regression model.

<u>Three sets of assumptions</u> define the *multiple* CLRM -- essentially the same three sets of assumptions that defined the *simple* CLRM, with one modification to assumption A8.

**1.** Assumptions respecting the **formulation of the** *population regression equation*, or PRE.

#### Assumption A1

2. Assumptions respecting the statistical properties of the *random error term* and the *dependent variable*.

# Assumptions A2-A4

- Assumption A2: The Assumption of Zero Conditional Mean Error
- Assumption A3: The Assumption of Constant Error Variances
- Assumption A4: The Assumption of Zero Error Covariances
- 3. Assumptions respecting the properties of the sample data.

## Assumptions A5-A8

- Assumption A5: The Assumption of *Independent Random Sampling*
- Assumption A6: The Assumption of *Sufficient Sample Data* (N > K)
- Assumption A7: The Assumption of Nonconstant Regressors
- Assumption A8: The Assumption of No Perfect Multicollinearity

# 2. Formulation of the Population Regression Equation (PRE)

## Assumption A1: The population regression equation, or PRE, takes the form

$$Y = \beta_0 + \beta_1 X_1 + \beta_2 X_2 + \dots + \beta_k X_k + u = \beta_0 + \sum_{j=1}^k \beta_j X_j + u$$
 (A1)

or

$$Y_{i} = \beta_{0} + \beta_{1}X_{1i} + \beta_{2}X_{2i} + \dots + \beta_{k}X_{ki} + u_{i} = \beta_{0} + \sum_{j=1}^{k}\beta_{j}X_{ji} + u_{i}$$
(A1)

The second form of (A1) writes the PRE for a particular observation i.

As in the simple CLRM, the PRE (A1) incorporates three distinct assumptions.

## A1.1: Assumption of an Additive Random Error Term.

 $\Rightarrow$  The random error term  $u_i$  enters the PRE <u>additively</u>.

$$\frac{\partial \mathbf{Y}_{i}}{\partial \mathbf{u}_{i}} = 1 \qquad \text{for all } i \ (\forall i).$$

# A1.2: Assumption of Linearity-in-Parameters or Linearity-in-Coefficients.

⇒ The PRE is *linear* in the population regression coefficients  $\beta_j$  (j = 0, ..., k).

Let  $\underline{\mathbf{x}}_i = \begin{bmatrix} 1 \ X_{1i} \ X_{2i} \ \cdots \ X_{ki} \end{bmatrix}$  be the (K×1) vector of regressor values for observation i.

$$\frac{\partial Y_i}{\partial \beta_j} = f_j(\underline{x}_i)$$
 where  $f_j(\underline{x}_i)$  contains *no unknown parameters*,  $j = 0, ..., k$ .

## A1.3: Assumption of Parameter or Coefficient Constancy.

 $\Rightarrow \quad \text{The population regression coefficients } \beta_j \ (j = 0, 1, ..., k) \ \text{are (unknown)} \\ \underline{\textit{constants}} \ \text{that do not vary across observations.}$ 

$$\beta_{ii} = \beta_i = \mathbf{a} \text{ constant } \forall \mathbf{i} \quad (\mathbf{j} = 0, 1, ..., \mathbf{k}).$$

# **3.** Properties of the Random Error Term

#### Assumption A2: The Assumption of Zero Conditional Mean Error

The *conditional mean*, or *conditional expectation*, of the random error terms  $u_i$  for any given values  $X_{ji}$  of the regressors  $X_j$  is equal to zero:

$$E(\mathbf{u} \mid \mathbf{X}_1, \mathbf{X}_2, \dots, \mathbf{X}_k) = E(\mathbf{u} \mid \underline{\mathbf{x}}) = 0$$
(A2)

or

$$E(\mathbf{u}_i | \mathbf{X}_{1i}, \mathbf{X}_{2i}, \dots, \mathbf{X}_{ki}) = E(\mathbf{u}_i | \underline{\mathbf{x}}_i) = 0 \quad \forall i$$
 (A2)

where  $\underline{\mathbf{x}} = \begin{bmatrix} 1 & X_1 & X_2 & \cdots & X_k \end{bmatrix}$  is any (K×1) vector of regressor values, and  $\underline{\mathbf{x}}_i = \begin{bmatrix} 1 & X_{1i} & X_{2i} & \cdots & X_{ki} \end{bmatrix}$  denotes the (K×1) vector of regressor values for a particular observation, namely observation i.

#### **Implications of Assumption A2**

• <u>Implication 1 of A2</u>. Assumption A2 implies that the *unconditional* mean of the population values of the random error term u equals *zero*:

$$E(u | \underline{x}) = 0 \implies E(u) = 0$$
 (A2-1)

or

$$E(\mathbf{u}_i | \underline{\mathbf{x}}_i) = 0 \implies E(\mathbf{u}_i) = 0 \quad \forall i.$$
 (A2-1)

This implication follows from the so-called **law of iterated expectations**, which states that  $E[E(u|\underline{x})] = E(u)$ . Since  $E(u|\underline{x}) = 0$  by A2, it follows that  $E(u) = E[E(u|\underline{x})] = E[0] = 0$ .

The logic of (A2-1) is straightforward: If the conditional mean of u for each and every population value of  $\underline{x}$  equals zero, then the mean of these zero conditional means must also be zero.

Implication 2 of A2: the Orthogonality Condition. Assumption A2 also implies that the population values X<sub>ji</sub> of the regressor X<sub>j</sub> and u<sub>i</sub> of the random error term u have zero covariance -- i.e., the population values of X<sub>j</sub> and u are uncorrelated:

$$E(\mathbf{u} | \underline{\mathbf{x}}) = 0 \implies Cov(\mathbf{X}_{j}, \mathbf{u}) = E(\mathbf{X}_{j} \mathbf{u}) = 0, \ j = 1, 2, ..., k$$
 (A2-2)

$$E(\mathbf{u}_i | \underline{\mathbf{x}}_i) = 0 \implies Cov(\mathbf{X}_{ji}, \mathbf{u}_i) = E(\mathbf{X}_{ji} \mathbf{u}_i) = 0 \forall i, j = 1, 2, ..., k \quad (A2-2)$$

**1.** The equality  $Cov(X_{ji}, u_i) = E(X_{ji}u_i)$  in (A2-2) follows from the definition of the covariance between  $X_{ji}$  and  $u_i$ , and from assumption (A2):

$$Cov(X_{ji}, u_i) \equiv E\{[X_{ji} - E(X_{ji})][u_i - E(u_i | \underline{x}_i)]\} \text{ by definition}$$
  
=  $E\{[X_{ji} - E(X_{ji})]u_i\} \text{ since } E(u_i | \underline{x}_i) = 0 \text{ by } A2$   
=  $E[X_{ji}u_i - E(X_{ji})u_i]$   
=  $E(X_{ji}u_i) - E(X_{ji})E(u_i) \text{ since } E(X_{ji}) \text{ is a constant}$   
=  $E(X_{ji}u_i) - E(X_{ji})E(u_i) \text{ since } E(u_i) = E(u_i | \underline{x}_i) = 0 \text{ by } A2.$ 

2. Implication (A2-2) states that the random error term u has zero covariance with, or is uncorrelated with, each of the regressors X<sub>j</sub> (j = 1, ..., k) in the population. This assumption means that there exists no <u>linear</u> association between u and any of the k regressors X<sub>j</sub> (j = 1, ..., k).

Note that *zero covariance* between  $X_{ji}$  and  $u_i$  implies *zero correlation* between  $X_{ji}$  and  $u_i$ , since the simple *correlation coefficient* between  $X_{ji}$  and  $u_i$ , denoted as  $\rho(X_{ji}, u_i)$ , is defined as

$$\rho(X_{ji}, u_i) \equiv \frac{\operatorname{Cov}(X_{ji}, u_i)}{\sqrt{\operatorname{Var}(X_{ji}) \operatorname{Var}(u_i)}} = \frac{\operatorname{Cov}(X_{ji}, u_i)}{\operatorname{sd}(X_{ji}) \operatorname{sd}(u_i)}.$$

From this definition of  $\rho(X_{ji}, u_i)$ , it is obvious that if  $Cov(X_{ji}, u_i) = 0$ , then  $\rho(X_{ji}, u_i) = 0$ , i.e.,

$$\operatorname{Cov}(X_{ji}, u_i) = 0 \quad \Longrightarrow \quad \rho(X_{ji}, u_i) = 0.$$

<u>Implication 3 of A2</u>. Assumption A2 implies that the *conditional mean* of the population Y<sub>i</sub> values corresponding to given values X<sub>ji</sub> of the regressors X<sub>j</sub> (j = 1, ..., k) equals the *population regression function (PRF)*:

$$E(\mathbf{u} | \underline{\mathbf{x}}) = 0 \implies E(\mathbf{Y} | \underline{\mathbf{x}}) = \mathbf{f}(\underline{\mathbf{x}}) = \beta_0 + \beta_1 \mathbf{X}_1 + \beta_2 \mathbf{X}_2 + \dots + \beta_k \mathbf{X}_k$$
$$= \beta_0 + \sum_{j=1}^k \beta_j \mathbf{X}_j \qquad (A2-3)$$

or

$$E(\mathbf{u}_{i} | \underline{\mathbf{x}}_{i}) = 0 \implies E(\mathbf{Y}_{i} | \underline{\mathbf{x}}_{i}) = f(\underline{\mathbf{x}}_{i}) = \beta_{0} + \beta_{1} \mathbf{X}_{1i} + \beta_{2} \mathbf{X}_{2i} + \dots + \beta_{k} \mathbf{X}_{ki}$$
$$= \beta_{0} + \sum_{j=1}^{k} \beta_{j} \mathbf{X}_{ji} \qquad \forall i. \qquad (A2-3)$$

**<u>Proof</u>**: Take the conditional expectation of the PRE (A1) for some given set of regressor values  $\underline{\mathbf{x}}_{i} = \begin{bmatrix} 1 \ X_{1i} \ X_{2i} \ \cdots \ X_{ki} \end{bmatrix}$ :

$$Y_{i} = \beta_{0} + \beta_{1}X_{1i} + \beta_{2}X_{2i} + \dots + \beta_{k}X_{ki} + u_{i} = \beta_{0} + \sum_{j=1}^{k}\beta_{j}X_{ji} + u_{i}$$
(A1)

$$\begin{split} E(Y_i | \underline{\mathbf{x}}_i) &= E(\beta_0 + \beta_1 X_{1i} + \beta_2 X_{2i} + \dots + \beta_k X_{ki} | \underline{\mathbf{x}}_i) + E(u_i | \underline{\mathbf{x}}_i) \\ &= E(\beta_0 + \beta_1 X_{1i} + \beta_2 X_{2i} + \dots + \beta_k X_{ki} | \underline{\mathbf{x}}_i) \quad \text{by A2, } E(u_i | \underline{\mathbf{x}}_i) = 0 \\ &= \beta_0 + \beta_1 X_{1i} + \beta_2 X_{2i} + \dots + \beta_k X_{ki} \\ &= \beta_0 + \sum_{j=1}^k \beta_j X_{ji} \quad \text{since } E\left(\beta_0 + \sum_{j=1}^k \beta_j X_{ji} | \underline{\mathbf{x}}_i\right) = \beta_0 + \sum_{j=1}^k \beta_j X_{ji}. \end{split}$$

#### • Meaning of the Zero Conditional Mean Error Assumption A2:

Each set of regressor values  $\underline{x}_i = \begin{bmatrix} 1 & X_{1i} & X_{2i} & \cdots & X_{ki} \end{bmatrix}$  identifies a segment or subset of the relevant population, specifically the segment that has those particular values of the regressors. For each of these population segments or subsets, assumption A2 says that the mean of the random error u is zero.

Assumption A2 rules out both *linear* dependence and *nonlinear* dependence between each  $X_j$  and u; that is, it requires that  $X_j$  and u be *statistically independent* for all j = 1, ..., k.

- The *absence* of *linear* dependence between  $X_j$  and u means that  $X_j$  and u are *uncorrelated*, or equivalently that  $X_j$  and u have zero covariance.
- But linear independence between  $X_j$  and u is not sufficient to guarantee the satisfaction of assumption A2. It is possible for  $X_j$  and u to be both uncorrelated, or linearly unrelated, and nonlinearly related.
- Assumption A2 therefore also requires that there be no nonlinear relationship between X<sub>j</sub> and u.
- <u>Violations of the Zero Conditional Mean Error Assumption A2</u>
- Remember that the random error term u represents all the unobservable, unmeasured and unknown variables other than the regressors  $X_j$ , j = 1, ..., k that determine the population values of the dependent variable Y.
- Anything that causes the random error u to be correlated with one or more of the regressors X<sub>j</sub> (j = 1, ..., k) will violate assumption A2:

$$\operatorname{Cov}(X_{j}, \mathbf{u}) \neq 0 \text{ or } \rho(X_{j}, \mathbf{u}) \neq 0 \implies \operatorname{E}(\mathbf{u} | \underline{\mathbf{x}}) \neq 0.$$

If  $X_j$  and u are correlated, then  $E(u|\underline{x})$  must depend on  $X_j$  and so cannot be zero.

Note that the converse is not true:

$$\operatorname{Cov}(X_j, u) = 0 \text{ or } \rho(X_j, u) = 0 \text{ for all } j \text{ does } not \text{ imply that } E(u | \underline{x}) = 0.$$

<u>*Reason*</u>:  $Cov(X_j, u)$  measures only *linear* dependence between u and  $X_j$ . But any *nonlinear* dependence between u and  $X_j$  will also cause  $E(u | \underline{x})$  to depend on  $X_j$ , and hence to differ from zero. So  $Cov(X_j, u) = 0$  for all j = 1, ..., k is not enough to insure that assumption A2 is satisfied.

- Common causes of correlation or dependence between the X<sub>j</sub> and u -- i.e., common causes of violations of assumption A2.
  - 1. Incorrect specification of the functional form of the relationship between Y and the  $X_j$ , j = 1, ..., k.

*Examples:* Using Y as the dependent variable when the true model has ln(Y) as the dependent variable. Or using  $X_j$  as the independent variable when the true model has  $ln(X_j)$  as the independent variable.

- 2. Omission of relevant variables that are correlated with one or more of the included regressors  $X_j$ , j = 1, ..., k.
- 3. Measurement errors in the regressors  $X_j$ , j = 1, ..., k.
- 4. Joint determination of one or more  $\mathbf{X}_j$  and  $\mathbf{Y}.$

# Assumption A3: The Assumption of Constant Error Variances The Assumption of Homoskedastic Errors The Assumption of Homoskedasticity

The *conditional variances* of the random error terms  $u_i$  are identical for all observations -- i.e., for all sets of regressor values  $\underline{x} = \begin{bmatrix} 1 & X_1 & X_2 & \cdots & X_k \end{bmatrix}$ ) -- and equal the same finite positive constant  $\sigma^2$  for all i:

$$\operatorname{Var}(\mathbf{u}|\underline{\mathbf{x}}) = \operatorname{E}(\mathbf{u}^{2}|\underline{\mathbf{x}}) = \sigma^{2} > 0 \tag{A3}$$

or

$$\operatorname{Var}\left(\mathbf{u}_{i} | \underline{\mathbf{x}}_{i}\right) = \operatorname{E}\left(\mathbf{u}_{i}^{2} | \underline{\mathbf{x}}_{i}\right) = \sigma^{2} > 0 \quad \forall i$$
(A3)

where  $\sigma^2$  is a *finite positive (unknown) constant* and  $\underline{x}_i = \begin{bmatrix} 1 & X_{1i} & X_{2i} & \cdots & X_{ki} \end{bmatrix}$  is the (K×1) vector of regressor values for observation i.

• The **first equality in A3** follows from the definition of the conditional variance of u<sub>i</sub> and assumption A2:

$$Var(\mathbf{u}_{i} | \underline{\mathbf{x}}_{i}) = E\{[\mathbf{u}_{i} - E(\mathbf{u}_{i} | \underline{\mathbf{x}}_{i})]^{2} | \underline{\mathbf{x}}_{i}\}$$
by definition  
$$= E\{[\mathbf{u}_{i} - \mathbf{0}]^{2} | \underline{\mathbf{x}}_{i}\}$$
because  $E(\mathbf{u}_{i} | \underline{\mathbf{x}}_{i}) = 0$  by assumption A2  
$$= E(\mathbf{u}_{i}^{2} | \underline{\mathbf{x}}_{i}).$$

• <u>Implication 1 of A3</u>: Assumption A3 implies that the *unconditional* variance of the random error u is also equal to  $\sigma^2$ :

$$\operatorname{Var}(\mathbf{u}_{i}) = \operatorname{E}\left[\left(\mathbf{u}_{i} - \operatorname{E}(\mathbf{u}_{i})\right)^{2}\right] = \operatorname{E}\left(\mathbf{u}_{i}^{2}\right) = \sigma^{2} \quad \forall i.$$

where  $Var(u_i) = E(u_i^2)$  because  $E(u_i) = 0$  by A2-1.

**<u>Proof</u>**: By assumptions A2 and A3,  $E(u_i^2 | \underline{x}_i) = \sigma^2$ . By *the law or iterated expectations*,  $E[E(u_i^2 | \underline{x}_i)] = E(u_i^2)$ . Thus,

$$\operatorname{Var}(\mathbf{u}_{i}) = \operatorname{E}(\mathbf{u}_{i}^{2}) = \operatorname{E}[\operatorname{E}(\mathbf{u}_{i}^{2} | \underline{\mathbf{x}}_{i})] = \operatorname{E}[\sigma^{2}] = \sigma^{2} \quad \forall i.$$

Implication 2 of A3: Assumption A3 implies that the conditional variance of the regressand Y<sub>i</sub> corresponding to given set of regressor values
 <u>x</u><sub>i</sub> = [1 X<sub>1i</sub> X<sub>2i</sub> ··· X<sub>ki</sub>] equals the conditional error variance σ<sup>2</sup>:

$$\operatorname{Var}(\mathbf{u} | \underline{\mathbf{x}}) = \sigma^2 > 0 \qquad \Rightarrow \qquad \operatorname{Var}(\mathbf{Y} | \underline{\mathbf{x}}) = \sigma^2 > 0. \qquad (A3-2)$$

or

$$\operatorname{Var}(\mathbf{u}_{i}|\underline{\mathbf{x}}_{i}) = \sigma^{2} > 0 \quad \forall i \quad \Rightarrow \quad \operatorname{Var}(\mathbf{Y}_{i}|\underline{\mathbf{x}}_{i}) = \sigma^{2} > 0 \quad \forall i.$$
 (A3-2)

**<u>Proof</u>**: Start with the definition of the conditional variance of  $Y_i$  for some given set (vector) of values of the regressors  $\underline{x}_i = \begin{bmatrix} 1 & X_{1i} & X_{2i} & \cdots & X_{ki} \end{bmatrix}$ .

$$\begin{aligned} \operatorname{Var}(\mathbf{Y}_{i} | \underline{\mathbf{x}}_{i}) &= \operatorname{E}\left\{ \left[ \mathbf{Y}_{i} - \operatorname{E}(\mathbf{Y}_{i} | \underline{\mathbf{x}}_{i})\right]^{2} | \underline{\mathbf{x}}_{i} \right\} & \text{by definition} \\ &= \operatorname{E}\left\{ \left[ \mathbf{Y}_{i} - \beta_{0} - \sum_{j=1}^{k} \beta_{j} \mathbf{X}_{ji} \right]^{2} | \underline{\mathbf{x}}_{i} \right\} & \text{since } \operatorname{E}(\mathbf{Y}_{i} | \underline{\mathbf{x}}_{i}) = \beta_{0} + \sum_{j=1}^{k} \beta_{j} \mathbf{X}_{ji} & \text{by A2} \\ &= \operatorname{E}\left(\mathbf{u}_{i}^{2} | \underline{\mathbf{x}}_{i}\right) & \text{since } \mathbf{u}_{i} = \mathbf{Y}_{i} - \beta_{0} - \sum_{j=1}^{k} \beta_{j} \mathbf{X}_{ji} & \text{by A1} \\ &= \sigma^{2} & \text{since } \operatorname{E}\left(\mathbf{u}_{i}^{2} | \underline{\mathbf{x}}_{i}\right) = \sigma^{2} & \text{by assumption A3.} \end{aligned}$$

# • <u>Meaning of the Homoskedasticity Assumption A3</u>

- For each set of regressor values, there is a *conditional* distribution of random errors, and a corresponding *conditional* distribution of population Y values.
- Assumption A3 says that the *variance* of the random errors for any particular set of regressor values <u>x</u><sub>i</sub> = [1 X<sub>1i</sub> X<sub>2i</sub> ··· X<sub>ki</sub>] is the *same* as the *variance* of the random errors for any other set of regressor values <u>x</u><sub>s</sub> = [1 X<sub>1s</sub> X<sub>2s</sub> ··· X<sub>ks</sub>] (for all <u>x</u><sub>s</sub> ≠ <u>x</u><sub>i</sub>).

In other words, the *variances* of the *conditional* random error distributions corresponding to each set of regressor values in the relevant population are all *equal* to the *same* finite positive constant  $\sigma^2$ .

$$\operatorname{Var}\left(\mathbf{u}_{i} | \underline{\mathbf{x}}_{i}\right) = \operatorname{Var}\left(\mathbf{u}_{s} | \underline{\mathbf{x}}_{s}\right) = \sigma^{2} > 0 \quad \text{ for all } \underline{\mathbf{x}}_{s} \neq \underline{\mathbf{x}}_{i}.$$

• Implication A3-2 says that the *variance* of the population Y values for  $\underline{x} = \underline{x}_i = \begin{bmatrix} 1 \ X_{1i} \ X_{2i} \ \cdots \ X_{ki} \end{bmatrix}$  is the *same* as the *variance* of the population Y values for any other set of regressor values  $\underline{x} = \underline{x}_s = \begin{bmatrix} 1 \ X_{1s} \ X_{2s} \ \cdots \ X_{ks} \end{bmatrix}$  (for all  $\underline{x}_s \neq \underline{x}_i$ ). The *conditional distributions* of the population Y values around the PRF have the *same constant* variance  $\sigma^2$  for all sets of regressor values.

$$\operatorname{Var}(Y_i | \underline{x}_i) = \operatorname{Var}(Y_s | \underline{x}_s) = \sigma^2 > 0 \quad \text{for all } \underline{x}_s \neq \underline{x}_i.$$

## **Assumption A4:** The Assumption of Zero Error Covariances The Assumption of Nonautoregressive Errors The Assumption of Nonautocorrelated Errors

Consider any pair of distinct random error terms  $u_i$  and  $u_s$  ( $i \neq s$ ) corresponding to two different sets (or vectors) of regressor values  $\underline{x}_i \neq \underline{x}_s$ . This assumption states that  $u_i$  and  $u_s$  have zero covariance:

$$\operatorname{Cov}(\mathbf{u}_{i},\mathbf{u}_{s}|\underline{\mathbf{x}}_{i},\underline{\mathbf{x}}_{s}) = E(\mathbf{u}_{i}\mathbf{u}_{s}|\underline{\mathbf{x}}_{i},\underline{\mathbf{x}}_{s}) = 0 \quad \forall i \neq s.$$
(A4)

• The **first equality in** (A4) follows from the definition of the conditional covariance of u<sub>i</sub> and u<sub>s</sub> and assumption (A2):

$$Cov(u_i, u_s | \underline{x}_i, \underline{x}_s) = E\{[u_i - E(u_i | \underline{x}_i)][u_s - E(u_s | \underline{x}_s)] | \underline{x}_i, \underline{x}_s\} \text{ by definition}$$
$$= E(u_i u_s | \underline{x}_i, \underline{x}_s) \text{ since } E(u_i | \underline{x}_i) = E(u_s | \underline{x}_s) = 0 \text{ by A2.}$$

- The **second equality in** (A4) states the assumption that all pairs of error terms corresponding to different sets of regressor values have zero covariance.
- Implication of A4: Assumption A4 implies that the conditional covariance of any two distinct values of the regressand, say Y<sub>i</sub> and Y<sub>s</sub> where i ≠ s, is equal to zero:

$$\operatorname{Cov}(\mathbf{u}_{i},\mathbf{u}_{s} | \underline{\mathbf{x}}_{i},\underline{\mathbf{x}}_{s}) = 0 \quad \forall \ i \neq s \quad \Longrightarrow \quad \operatorname{Cov}(\mathbf{Y}_{i},\mathbf{Y}_{s} | \underline{\mathbf{x}}_{i},\underline{\mathbf{x}}_{s}) = 0 \quad \forall \ i \neq s.$$

**Proof**: Show that 
$$\operatorname{Cov}(Y_i, Y_s | \underline{x}_i, \underline{x}_s) = E(u_i u_s | \underline{x}_i, \underline{x}_s) = \operatorname{Cov}(u_i, u_s | \underline{x}_i, \underline{x}_s).$$

(1) Begin with the definition of the conditional covariance for  $Y_i$  and  $Y_s$  for given  $\underline{x}_i$  and  $\underline{x}_s$  values where  $\underline{x}_i \neq \underline{x}_s$ :

$$Cov(\mathbf{Y}_{i}, \mathbf{Y}_{s} | \underline{\mathbf{x}}_{i}, \underline{\mathbf{x}}_{s}) \equiv E\{ [\mathbf{Y}_{i} - E(\mathbf{Y}_{i} | \underline{\mathbf{x}}_{i})] [\mathbf{Y}_{s} - E(\mathbf{Y}_{s} | \underline{\mathbf{x}}_{s})] | \underline{\mathbf{x}}_{i}, \underline{\mathbf{x}}_{s} \}$$
$$= E(\mathbf{u}_{i} \mathbf{u}_{s} | \underline{\mathbf{x}}_{i}, \underline{\mathbf{x}}_{s})$$

since

$$\begin{split} &Y_{i} - E(Y_{i} | \underline{x}_{i}) = Y_{i} - \beta_{0} - \sum_{j=1}^{k} \beta_{j} X_{ji} = u_{i} & \text{by assumption A1,} \\ &Y_{s} - E(Y_{s} | \underline{x}_{s}) = Y_{s} - \beta_{0} - \sum_{j=1}^{k} \beta_{j} X_{js} = u_{s} & \text{by assumption A1.} \end{split}$$

(2) Therefore

$$\operatorname{Cov}(Y_i, Y_s | \underline{x}_i, \underline{x}_s) = E(u_i u_s | \underline{x}_i, \underline{x}_s) = 0$$
 by assumption A4.

- Meaning of A4: Assumption A4 means that there is no systematic *linear* association between u<sub>i</sub> and u<sub>s</sub>, or between Y<sub>i</sub> and Y<sub>s</sub>, where i and s correspond to different observations (or different sets of regressor values x<sub>i</sub> ≠ x<sub>s</sub>).
  - 1. Each random error term  $u_i$  has *zero covariance with*, or *is uncorrelated with*, each and every other random error term  $u_s$  (s  $\neq$  i).
  - 2. Equivalently, each regressand value  $Y_i$  has *zero covariance with*, or *is uncorrelated with*, each and every other regressand value  $Y_s$  (s  $\neq$  i).
  - The **assumption of** *zero covariance*, or *zero correlation*, between each pair of distinct observations is *weaker* than the **assumption of** *independent random sampling A5* from an underlying population.
  - The **assumption of** *independent random sampling* implies that the sample observations are statistically independent. The **assumption of** *statistically independent observations* is *sufficient* for the assumption of *zero covariance* between observations, but is stronger than necessary.

# 4. Properties of the Sample Data

# Assumption A5: Random Sampling or Independent Random Sampling

The **sample data** consist of **N** *randomly selected observations* on the regressand Y and the regressors  $X_j$  (j = 1, ..., k), the observable variables in the PRE described by A1. These N randomly selected observations can be written as N row vectors:

Sample data 
$$\equiv \left[ (\mathbf{Y}_1, \underline{\mathbf{x}}_1), (\mathbf{Y}_2, \underline{\mathbf{x}}_2), \dots, (\mathbf{Y}_N, \underline{\mathbf{x}}_N) \right]$$
$$\equiv \left( \mathbf{Y}_i, \mathbf{1}, \mathbf{X}_{1i}, \mathbf{X}_{2i}, \dots, \mathbf{X}_{ki} \right) \qquad i = 1, \dots, N$$
$$\equiv \left( \mathbf{Y}_i, \underline{\mathbf{x}}_i \right) \qquad i = 1, \dots, N.$$

• Implications of the Random Sampling Assumption A5

The assumption of random sampling implies that the sample observations are *statistically independent*.

1. It thus means that the error terms **u**<sub>i</sub> and **u**<sub>s</sub> are *statistically independent*, and hence **have** *zero covariance*, for any two observations i and s.

Random sampling  $\Rightarrow Cov(u_i, u_s | \underline{x}_i, \underline{x}_s) = Cov(u_i, u_s) = 0 \quad \forall i \neq s.$ 

It also means that the dependent variable values Y<sub>i</sub> and Y<sub>s</sub> are *statistically independent*, and hence have *zero covariance*, for any two observations i and s.

Random sampling  $\Rightarrow Cov(Y_i, Y_s | \underline{x}_i, \underline{x}_s) = Cov(Y_i, Y_s) = 0 \quad \forall i \neq s.$ 

The assumption of random sampling is therefore sufficient for assumption A4 of zero covariance between observations, but is stronger than necessary.

# • <u>When is the Random Sampling Assumption A5 Appropriate?</u>

The random sampling assumption is often appropriate for *cross-sectional* **regression models**, but is hardly ever appropriate for *time-series* **regression models**.

<u>Assumption A6</u>: The number of sample observations N is greater than the number of unknown parameters K:

number of sample observations > number of unknown parameters

$$N > K.$$
 (A6)

• <u>Meaning of A6</u>: Unless this assumption is satisfied, it is not possible to compute from a given sample of N observations estimates of all the unknown parameters in the model.

## Assumption A7: Nonconstant Regressors

The sample values  $X_{ji}$  of each regressor  $X_j$  (j = 1, ..., k) in a given sample (and hence in the population) are not all equal to a constant:

$$X_{ji} \neq c_j \quad \forall i = 1, ..., N$$
 where the  $c_j$  are constants  $(j = 1, ..., k)$ . (A7)

<u>Technical Form of A7</u>: Assumption A7 requires that the *sample* variances of all k–1 non-constant regressors X<sub>j</sub> (j = 1, ..., k) must be *finite positive* numbers for any sample size N; i.e.,

sample variance of 
$$X_{ji} = Var(X_{ji}) = \frac{\sum_{i} (X_{ji} - \overline{X}_{j})^2}{N-1} = s_{X_j}^2 > 0$$
,

where  $s_{x_i}^2 > 0$  are *finite positive* numbers for all j = 1, ..., k.

• <u>Meaning of A7</u>: Assumption A7 requires that each nonconstant regressor  $X_j$ (j = 1, ..., k) takes at least *two* different values in any given sample.

Unless this assumption is satisfied, it is not possible to compute from the sample data an estimate of the effect on the regressand Y of changes in the value of the regressor  $X_j$ . In other words, to calculate the effect of changes in  $X_j$  on Y, the sample values  $X_{ji}$  of the regressor  $X_j$  must vary across observations in any given sample.

# Assumption A8: No Perfect Multicollinearity

The sample values of the regressors  $X_j$  (j = 1, ..., k) in a multiple regression model do *not* exhibit *perfect or exact multicollinearity*.

This assumption is relevant only in *multiple* regression models that contain two or more non-constant regressors.

This assumption is the only new assumption required for the multiple linear regression model.

- <u>Statement of Assumption A8</u>: The absence of *perfect multicollinearity* means that there exists **no** *exact linear* **relationship** among the **sample values** of the non-constant regressors  $X_j$  (j = 1, ..., k).
  - An exact linear relationship exists among the sample values of the nonconstant regressors if the sample values of the regressors X<sub>j</sub> (j = 1, ..., k) satisfy a linear relationship of the form

$$\lambda_0 + \lambda_1 X_{1i} + \lambda_2 X_{2i} + \dots + \lambda_k X_{ki} = 0 \qquad \forall i = 1, 2, \dots, N.$$

$$(1)$$

where the  $\lambda_i$  (j = 0, 1, ..., k) are **fixed constants**, not all of which equal zero.

- Assumption A8 the absence of perfect multicollinearity means that there exists no relationship of the form (1) among the sample values X<sub>ji</sub> of the regressors X<sub>j</sub> (j = 1, ..., k).
- <u>Meaning of Assumption A8</u>:
  - Each non-constant regressor X<sub>j</sub> (j = 1, ..., k) must exhibit some *independent* linear variation in the sample data.
  - Otherwise, it is not possible to estimate the *separate* linear effect of each and every non-constant regressor on the regressand Y.

## • Example of Perfect Multicollinearity

Consider the following multiple linear regression model:

$$Y_{i} = \beta_{0} + \beta_{1}X_{1i} + \beta_{2}X_{2i} + u_{i} \qquad (i = 1, ..., N).$$
(2)

Suppose that the sample values of the regressors  $X_{1i}$  and  $X_{2i}$  satisfy the following linear equality for all sample observations:

$$X_{1i} = 3X_{2i}$$
 or  $X_{1i} - 3X_{2i} = 0 \forall i = 1,...,N.$  (3)

The exact linear relationship (3) can be written in the general form (1).

1. For the linear regression model given by PRE (2), equation (1) takes the form

$$\lambda_0 + \lambda_1 X_{1i} + \lambda_2 X_{2i} = 0 \qquad \forall i = 1, 2, \dots, N.$$

2. Set  $\lambda_0 = 0$ ,  $\lambda_1 = 1$ , and  $\lambda_2 = -3$  in the above equation:

 $X_{1i} - 3X_{2i} = 0 \quad \forall i = 1, 2, ..., N.$  (identical to equation (3) above.)

## <u>Consequences of Perfect Multicollinearity</u>

**1.** Substitute for  $X_{1i}$  in PRE (2) the equivalent expression  $X_{1i} = 3X_{2i}$ :

$$\begin{aligned} Y_{i} &= \beta_{0} + \beta_{1} X_{1i} + \beta_{2} X_{2i} + u_{i} \\ &= \beta_{0} + \beta_{1} (3X_{2i}) + \beta_{2} X_{2i} + u_{i} \\ &= \beta_{0} + 3\beta_{1} X_{2i} + \beta_{2} X_{2i} + u_{i} \\ &= \beta_{0} + (3\beta_{1} + \beta_{2}) X_{2i} + u_{i} \\ &= \beta_{0} + \alpha_{2} X_{2i} + u_{i} \end{aligned}$$
 (4a)

- It is possible to estimate from the sample data the regression coefficients β<sub>0</sub> and α<sub>2</sub>.
- But from the estimate of α<sub>2</sub> it is not possible to compute estimates of the coefficients β<sub>1</sub> and β<sub>2</sub>. <u>*Reason*</u>: The equation

$$\alpha_2 = 3\beta_1 + \beta_2$$

is *one* equation containing *two* unknowns, namely  $\beta_1$  and  $\beta_2$ .

<u>**Result</u></u>: It is not possible to compute from the sample data estimates of** *both* **\beta\_1 and \beta\_2, the separate linear effects of X\_{1i} and X\_{2i} on the regressand Y\_i.</u>** 

- 2. Alternatively, substitute for X<sub>2i</sub> in PRE (2) the equivalent expression  $X_{2i} = \frac{X_{1i}}{3}:$   $Y_{i} = \beta_{0} + \beta_{1}X_{1i} + \beta_{2}X_{2i} + u_{i}$   $= \beta_{0} + \beta_{1}X_{1i} + \beta_{2}\left(\frac{X_{1i}}{3}\right) + u_{i}$   $= \beta_{0} + \beta_{1}X_{1i} + \frac{\beta_{2}}{3}X_{1i} + u_{i}$   $= \beta_{0} + \left(\beta_{1} + \frac{\beta_{2}}{3}\right)X_{1i} + u_{i}$   $= \beta_{0} + \alpha_{1}X_{1i} + u_{i}$ where  $\alpha_{1} = \beta_{1} + \frac{\beta_{2}}{3}$ . (4b)
- It is possible to estimate from the sample data the regression coefficients β<sub>0</sub> and α<sub>1</sub>.
- But from the estimate of α<sub>1</sub> it is not possible to compute estimates of the coefficients β<sub>1</sub> and β<sub>2</sub>. <u>*Reason*</u>: The equation

$$\alpha_1 = \beta_1 + \frac{\beta_2}{3}$$

is *one* equation containing *two* unknowns, namely  $\beta_1$  and  $\beta_2$ .

<u>**Result</u>**: Again, it is not possible to compute from the sample data estimates of **both**  $\beta_1$  and  $\beta_2$ , the separate linear effects of  $X_{1i}$  and  $X_{2i}$  on the regressand  $Y_i$ .</u>

# 5. Interpreting Slope Coefficients in Multiple Linear Regression Models

• Consider the multiple linear regression model given by the following **population regression equation (PRE)**:

$$Y_{i} = \beta_{0} + \beta_{1}X_{1i} + \beta_{2}X_{2i} + \beta_{3}X_{3i} + u_{i}$$
(5)

 $X_1$ ,  $X_2$  and  $X_3$  are three distinct independent or explanatory variables that determine the population values of Y.

Because regression equation (5) contains more than one regressor, it is called a *multiple* linear regression model.

• The population regression function (PRF) corresponding to PRE (5) is:

$$E(Y_{i} | \underline{x}_{i}) = E(Y_{i} | X_{1i}, X_{2i}, X_{3i}) = \beta_{0} + \beta_{1}X_{1i} + \beta_{2}X_{2i} + \beta_{3}X_{3i}$$
(6)

where  $\underline{x}_i$  is the 1×4 row vector of regressors:  $\underline{x}_i = (1 X_{1i} X_{2i} X_{3i})$ .

#### □ Interpreting the Slope Coefficients in Multiple Regression Model (5)

Each *slope* coefficient β<sub>j</sub> is the *marginal* effect of the corresponding explanatory variable X<sub>j</sub> on the conditional mean of Y. Formally, the *slope* coefficients {β<sub>j</sub> : j = 1, 2, 3} are the *partial derivatives* of the population regression function (PRF) with respect to the explanatory variables {X<sub>j</sub> : j = 1, 2, 3}:

$$\frac{\partial E(Y_i | \underline{x}_i)}{\partial X_{ji}} = \frac{\partial E(Y_i | X_{1i}, X_{2i}, X_{3i})}{\partial X_{ji}} = \beta_j \qquad j = 1, 2, 3$$
(7)

For example, for j = 1 in multiple regression model (5):

$$\frac{\partial E(Y_i | X_{1i}, X_{2i}, X_{3i})}{\partial X_{1i}} = \frac{\partial (\beta_0 + \beta_1 X_{1i} + \beta_2 X_{2i} + \beta_3 X_{3i})}{\partial X_{1i}} = \beta_1$$
(8)

• *Interpretation:* A *partial* derivative isolates the marginal effect on the conditional mean of Y of small variations in one of the explanatory variables, while *holding constant* the values of the *other* explanatory variables in the PRF.

*Example:* In multiple regression model (5)

$$Y_{i} = \beta_{0} + \beta_{1}X_{1i} + \beta_{2}X_{2i} + \beta_{3}X_{3i} + u_{i}$$
(5)

with population regression function

$$E(Y_{i} | X_{1i}, X_{2i}, X_{3i}) = \beta_{0} + \beta_{1}X_{1i} + \beta_{2}X_{2i} + \beta_{3}X_{3i}$$
(6)

the *slope* coefficients  $\beta_1$ ,  $\beta_2$  and  $\beta_3$  are interpreted as follows:

- $\beta_1$  = the *partial* marginal effect of X<sub>1</sub> on the conditional mean of Y *holding constant* the values of the other regressors X<sub>2</sub> and X<sub>3</sub>.
- $\beta_2$  = the *partial* marginal effect of X<sub>2</sub> on the conditional mean of Y *holding constant* the values of the other regressors X<sub>1</sub> and X<sub>3</sub>.
- $\beta_3$  = the *partial* marginal effect of X<sub>3</sub> on the conditional mean of Y *holding constant* the values of the other regressors X<sub>1</sub> and X<sub>2</sub>.
- Including X<sub>2</sub> and X<sub>3</sub> in the regression function allows us to estimate the partial marginal effect of X<sub>1</sub> on E(Y | X<sub>1</sub>, X<sub>2</sub>, X<sub>3</sub>) while
  - holding constant the values of X<sub>2</sub> and X<sub>3</sub>
  - controlling for the effects on Y of X<sub>2</sub> and X<sub>3</sub>
  - **conditioning** on  $X_2$  and  $X_3$ .

#### **\Box** Interpreting the Slope Coefficient $\beta_1$ in Multiple Regression Model (5)

$$Y_{i} = \beta_{0} + \beta_{1}X_{1i} + \beta_{2}X_{2i} + \beta_{3}X_{3i} + u_{i}$$
(5)

$$E(Y_{i} | X_{1i}, X_{2i}, X_{3i}) = \beta_{0} + \beta_{1}X_{1i} + \beta_{2}X_{2i} + \beta_{3}X_{3i}$$
(6)

• Denote the *initial* values of the explanatory variables X<sub>1</sub>, X<sub>2</sub> and X<sub>3</sub> as X<sub>10</sub>, X<sub>20</sub> and X<sub>30</sub>.

The *initial* value of the population regression function for  $\mathbf{Y}$  for the initial values of  $X_1$ ,  $X_2$  and  $X_3$  is:

$$E(Y|X_{10}, X_{20}, X_{30}) = \beta_0 + \beta_1 X_{10} + \beta_2 X_{20} + \beta_3 X_{30}$$
(9)

• Now change the value of the explanatory variable  $X_1$  by  $\Delta X_1$ , while holding constant the values of the other two explanatory variables  $X_2$  and  $X_3$  at their initial values  $X_{20}$  and  $X_{30}$ .

The *new* value of X<sub>1</sub> is therefore

$$\mathbf{X}_{11} = \mathbf{X}_{10} + \Delta \mathbf{X}_{11}$$

The *change* in the value of X<sub>1</sub> is thus

$$\Delta X_1 = X_{11} - X_{10}$$

The *new* value of the population regression function for  $\mathbf{Y}$  at the new value of the explanatory variable  $X_1$  is:

$$E(Y | X_{11}, X_{20}, X_{30}) = \beta_0 + \beta_1 X_{11} + \beta_2 X_{20} + \beta_3 X_{30}$$
  
=  $\beta_0 + \beta_1 (X_{10} + \Delta X_1) + \beta_2 X_{20} + \beta_3 X_{30}$   
=  $\beta_0 + \beta_1 X_{10} + \beta_1 \Delta X_1 + \beta_2 X_{20} + \beta_3 X_{30}$  (10)

The *change* in the conditional mean value of Y associated with the change ΔX<sub>1</sub> in the value of X<sub>1</sub> is obtained by subtracting the initial value of the population regression function given by (9) from the new value of the population regression function given by (10):

$$\Delta E(Y | X_{1}, X_{2}, X_{3}) = E(Y | X_{11}, X_{20}, X_{30}) - E(Y | X_{10}, X_{20}, X_{30})$$

$$= \beta_{0} + \beta_{1} X_{10} + \beta_{1} \Delta X_{1} + \beta_{2} X_{20} + \beta_{3} X_{30}$$

$$- (\beta_{0} + \beta_{1} X_{10} + \beta_{2} X_{20} + \beta_{3} X_{30})$$

$$= \beta_{0} + \beta_{1} X_{10} + \beta_{1} \Delta X_{1} + \beta_{2} X_{20} + \beta_{3} X_{30}$$

$$- \beta_{0} - \beta_{1} X_{10} - \beta_{2} X_{20} - \beta_{3} X_{30}$$

$$= \beta_{1} \Delta X_{1}$$
(11)

The *interpretation* of the slope coefficient β<sub>1</sub> is obtained by solving for β<sub>1</sub> in (11):

$$\beta_{1} = \left(\frac{\Delta E(Y | X_{1}, X_{2}, X_{3})}{\Delta X_{1}}\right)_{\Delta X_{2}=0, \Delta X_{3}=0} = \frac{\partial E(Y | X_{1}, X_{2}, X_{3})}{\partial X_{1}}$$

# $\beta_1$ = the *partial* marginal effect of X<sub>1</sub> on the conditional mean of Y holding constant the values of the other regressors X<sub>2</sub> and X<sub>3</sub>.

## **Comparing Slope Coefficients in Simple and Multiple Regression Models**

• Compare the *multiple* linear regression model

$$Y_{i} = \beta_{0} + \beta_{1}X_{1i} + \beta_{2}X_{2i} + \beta_{3}X_{3i} + u_{i}$$
(5)

with the *simple* linear regression model

$$Y_{i} = \beta_{0} + \beta_{1}X_{1i} + u_{i}$$
(12)

- *Question:* What is the difference between the slope coefficient β<sub>1</sub> in these two regression models?
- Answer: Compare the population regression functions for these two models.

For the multiple regression model (5), the population regression function is

$$E(Y|X_{1i}, X_{2i}, X_{3i}) = \beta_0 + \beta_1 X_{1i} + \beta_2 X_{2i} + \beta_3 X_{3i}$$
(6)

As we have seen, the slope coefficient  $\beta_1$  in multiple regression model (5) is

$$\beta_1 \text{ in model } (5) = \left(\frac{\Delta E(Y | X_1, X_2, X_3)}{\Delta X_1}\right)_{\Delta X_2 = 0, \Delta X_3 = 0} = \frac{\partial E(Y | X_1, X_2, X_3)}{\partial X_1}$$

For the simple regression model (12), the population regression function is

$$E(\mathbf{Y} \,|\, \mathbf{X}_{1i}) = \boldsymbol{\beta}_0 + \boldsymbol{\beta}_1 \mathbf{X}_{1i}$$

The slope coefficient  $\beta_1$  in simple regression model (12) is

$$\beta_1 \text{ in model } (12) = \frac{\Delta E(Y | X_1)}{\Delta X_1} = \frac{d E(Y | X_1)}{d X_1}$$

# • Compare $\beta_l$ in model (5) with $\beta_l$ in model (12)

 $\beta_1$  in multiple regression model (5) controls for – or accounts for – the effects of  $X_2$  and  $X_3$  on the conditional mean value of the dependent variable Y.

# $\beta_1$ in *multiple* regression model (5) is therefore referred to as the *adjusted* marginal effect of $X_1$ on Y.

 $\beta_1$  in simple regression model (12) does not control for – or account for – the effects of  $X_2$  and  $X_3$  on the conditional mean value of the dependent variable Y.

 $\beta_1$  in *simple* regression model (12) is therefore referred to as the *unadjusted* marginal effect of  $X_1$  on Y.