ECON 452* -- NOTE 10

<u>Testing Linear Coefficient Restrictions in Linear Regression</u> <u>Models: The Fundamentals</u>

This note outlines the fundamentals of statistical inference in linear regression models.

• **In scalar notation**, the population regression equation, or PRE, for the linear regression model is written in general as:

$$Y_{i} = \beta_{0} + \beta_{1}X_{i1} + \beta_{2}X_{i2} + \dots + \beta_{k}X_{ik} + u_{i} \qquad \forall i$$
(1.1)

or

$$Y_{i} = \beta_{0} + \sum_{j=1}^{j=k} \beta_{j} X_{ij} + u_{i} \qquad \qquad \forall i \qquad (1.2)$$

or

$$Y_{i} = \sum_{j=0}^{j=k} \beta_{j} X_{ij} + u_{i}, \quad X_{i0} = 1 \ \forall i \qquad \forall i$$
 (1.3)

where

- $Y_i =$ the i-th population value of the regressand, or dependent variable;
- $X_{ij} \equiv$ the i-th population value of the j-th regressor, j = 1, ..., k;
- $\beta_j \equiv$ the partial slope coefficient of X_{ij} , j = 1, ..., k;

 $u_i \equiv$ the i-th population value of the unobservable random error term.

• **In vector-matrix notation**, the population regression equation, or PRE, for a sample of N observations on a linear regression model can be written as:

$$y = X\beta + u \tag{2}$$

where

$$y = \begin{bmatrix} Y_1 \\ Y_2 \\ Y_3 \\ \vdots \\ Y_N \end{bmatrix} = \text{ the N \times 1 regressand vector}$$

= the N×1 <u>column</u> vector of observed sample values of the regressand, or dependent variable, Y_i (i = 1, ..., N);

$$\mathbf{u} = \begin{bmatrix} \mathbf{u}_1 \\ \mathbf{u}_2 \\ \mathbf{u}_3 \\ \vdots \\ \mathbf{u}_N \end{bmatrix} = \text{ the N \times 1 error vector}$$

= the N×1 <u>column</u> vector of unobserved random error terms u_i (i = 1, ..., N) corresponding to each of the N sample observations.

$$\mathbf{X} = \begin{bmatrix} \mathbf{x}_{1}^{\mathrm{T}} \\ \mathbf{x}_{2}^{\mathrm{T}} \\ \mathbf{x}_{3}^{\mathrm{T}} \\ \vdots \\ \mathbf{x}_{N}^{\mathrm{T}} \end{bmatrix} = \begin{bmatrix} 1 & X_{11} & X_{12} & \cdots & X_{1k} \\ 1 & X_{21} & X_{22} & \cdots & X_{2k} \\ 1 & X_{31} & X_{32} & \cdots & X_{3k} \\ \vdots & \vdots & \vdots & \cdots & \vdots \\ 1 & X_{N1} & X_{N2} & \cdots & X_{Nk} \end{bmatrix} = \text{ the N} \times \text{K regressor matrix}$$

= the N×K matrix of observed sample values of the K = k + 1regressors X_{i0} , X_{i1} , X_{i2} , ..., X_{ik} (i = 1, ..., N), where the first regressor is a constant equal to 1 for all observations ($X_{i0} = 1 \forall i = 1, ..., N$).

$$\beta = \begin{bmatrix} \beta_0 \\ \beta_1 \\ \beta_2 \\ \vdots \\ \beta_k \end{bmatrix} = \text{ the K} \times 1 \text{ regression coefficient vector}$$

- = the K×1 or (k+1)×1<u>column</u> vector of unknown partial regression coefficients β_j , j = 0, 1, ..., k.
- **Statistical inference** consists of both
 - 1. testing hypotheses on the regression coefficient vector β and
 - 2. constructing confidence intervals for the individual elements of β .

1. Assumption A6: The Error Normality Assumption

In order to perform statistical inference in the linear regression model, it is necessary to specify the form of the probability distribution of the error vector u in population regression equation (1). The normality assumption does this.

□ Scalar Formulation of the Error Normality Assumption A6

The random error terms u_i are *independently* and *identically* distributed as the *normal* distribution with

1. zero conditional means

$$\mathbf{E}(\mathbf{u}_{i} | \mathbf{x}_{i}^{\mathrm{T}}) = \mathbf{E}(\mathbf{u}_{i}) = \mathbf{0} \qquad \forall i$$

2. constant conditional variances

$$Var(u_{i} | x_{i}^{T}) = E(u_{i}^{2} | x_{i}^{T}) = E(u_{i}^{2} | 1, X_{i1}, X_{i2}, ..., X_{ik}) = \sigma^{2} > 0 \qquad \forall i$$

3. zero conditional covariances

 $Cov\left(u_{i},u_{s}\right|\left.x_{i}^{T},\,x_{s}^{T}\right)=\,E\left(u_{i}u_{s}\right|\left.x_{i}^{T},\,x_{s}^{T}\right)=\,0\qquad \forall\ i\neq s$

• A compact way of stating error normality assumption A6 is: conditional on x_i^T , the u_i are iid as N(0, σ^2) (A6.1)

where

"iid" means "*independently* and *identically* distributed" N(0, σ^2) denotes a normal distribution with zero mean and variance σ^2 . Even more briefly, we can say that

$$\mathbf{u}_{i} \mid \mathbf{x}_{i}^{\mathrm{T}}$$
 are iid as N(0, σ^{2}). (A6.2)

□ Matrix Formulation of the Error Normality Assumption A6

The N×1 error vector u has a multivariate normal distribution with

1. a zero conditional mean vector

 $E(u | X) = \underline{0}$ where $\underline{0}$ is an N×1 vector of zeros

2. a constant scalar diagonal covariance matrix V(u)

 $V(u \,|\, X) = E(uu^{T} \,|\, X) = \sigma^{2}I_{N} \quad \text{where } I_{N} \text{ is the } N \times N \text{ identity matrix}$

• A compact way of stating the error normality assumption in matrix terms is:

$$\mathbf{u} \left| \mathbf{X} \sim \mathbf{N} \left(\underline{\mathbf{0}}, \sigma^2 \mathbf{I}_{\mathbf{N}} \right) \right|$$
 (A6)

where $N(\cdot, \cdot)$ here denotes the N-variate normal distribution.

- □ Implications of Assumption A6 for the Distribution of the Regressand Vector y
- Linearity Property of Normal Distribution: Any linear function of a normally distributed random variable is itself normally distributed.
- y is a linear function of u: The PRE $y = X\beta + u$ states that the regressand vector y is a linear function of the error vector u.
- *Implication:* Since u is normally distributed by assumption A6 and y is a linear function of u by assumption A1, the linearity property of the normal distribution implies that

$$y | X \sim N(X\beta, \sigma^2 I_N).$$

That is, the regressand vector y has an N-variate normal distribution with

(1) conditional mean vector equal to $E(y|X) = X\beta$

and

(2) conditional covariance matrix equal to $V(y|X) = \sigma^2 I_N$.

- $\hat{\beta}$ is a linear function of y. Conditional on the regressors X, the OLS coefficient estimator $\hat{\beta}$ is a linear function of the regressand vector y:

 $\hat{\boldsymbol{\beta}} = \left(\boldsymbol{X}^{\mathrm{T}} \boldsymbol{X} \right)^{\!\!-1} \! \boldsymbol{X}^{\mathrm{T}} \boldsymbol{y}$

• *Implication:* Since y is normally distributed by implication of assumption A6 and $\hat{\beta}$ is a linear function of y, the linearity property of the normal distribution implies that

$$\hat{\beta} | X \sim N(\beta, \sigma^2 (X^T X)^{-1}).$$
(3)

That is, the **OLS coefficient estimator** $\hat{\beta}$ has an K-variate *normal* **distribution** with

(1) conditional mean vector equal to $E(\hat{\beta} | X) = \beta$

and

(2) conditional covariance matrix equal to $V(\hat{\beta} | X) = \sigma^2 (X^T X)^{-1}$.

2. Formulation of Linear Equality Restrictions on β

The general hypothesis to be tested is that the coefficient vector β satisfies a set of q independent linear restrictions, where q < K. We formulate this general hypothesis in vector-matrix form, since this corresponds to the way in which econometric software such as *Stata* is written.

The **null hypothesis** H_0 is written in general as:

 $H_0: \quad R\beta = r \quad \Longleftrightarrow \quad R\beta - r = \underline{0}$

The alternative hypothesis H_1 is written in general as:

 $H_1 : \quad R\beta \neq r \quad \Longleftrightarrow \quad R\beta - r \neq \underline{0}$

In H_0 and H_1 above:

 $R = a q \times K$ matrix of specified constants;

 β = the K×1 coefficient vector;

 $r = a q \times 1$ vector of specified constants;

 $\underline{0} = a q \times 1$ null vector, i.e., $a q \times 1$ vector of zeros.

• The q×K restrictions matrix R takes the form

 $\mathbf{R} = \begin{bmatrix} \mathbf{r}_{10} & \mathbf{r}_{11} & \mathbf{r}_{12} & \cdots & \mathbf{r}_{1k} \\ \mathbf{r}_{20} & \mathbf{r}_{21} & \mathbf{r}_{22} & \cdots & \mathbf{r}_{2k} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ \mathbf{r}_{q0} & \mathbf{r}_{q1} & \mathbf{r}_{q2} & \cdots & \mathbf{r}_{qk} \end{bmatrix}$

where

 r_{mj} = the constant on coefficient β_j in the m-th linear restriction, m = 1, ..., q.

• The $q \times 1$ restrictions vector r takes the form

$$\mathbf{r} = \begin{bmatrix} \mathbf{r}_1 \\ \mathbf{r}_2 \\ \vdots \\ \mathbf{r}_q \end{bmatrix}$$

where

 r_m = the constant term in the m-th linear restriction, m = 1, ..., q.

The matrix-vector product Rβ is a q×1 vector of linear functions of the regression coefficients β₀, β₁, β₂, ..., β_k:

$$R\beta = \begin{bmatrix} r_{10} & r_{11} & r_{12} & \cdots & r_{1k} \\ r_{20} & r_{21} & r_{22} & \cdots & r_{2k} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ r_{q0} & r_{q1} & r_{q2} & \cdots & r_{qk} \end{bmatrix} \begin{bmatrix} \beta_0 \\ \beta_1 \\ \beta_2 \\ \vdots \\ \beta_k \end{bmatrix} = \begin{bmatrix} r_{10}\beta_0 + r_{11}\beta_1 + r_{12}\beta_2 + \cdots + r_{1k}\beta_k \\ r_{20}\beta_0 + r_{21}\beta_1 + r_{22}\beta_2 + \cdots + r_{2k}\beta_k \\ \vdots \\ r_{q0}\beta_0 + r_{q1}\beta_1 + r_{q2}\beta_2 + \cdots + r_{qk}\beta_k \end{bmatrix}$$

$$(q \times K) \qquad (K \times 1) \qquad (q \times 1)$$

• The null and alternative hypotheses can therefore be written as follows:

$$H_{0}: R\beta = r \implies \begin{bmatrix} r_{10}\beta_{0} + r_{11}\beta_{1} + r_{12}\beta_{2} + \dots + r_{1k}\beta_{k} \\ r_{20}\beta_{0} + r_{21}\beta_{1} + r_{22}\beta_{2} + \dots + r_{2k}\beta_{k} \\ \vdots \end{bmatrix} = \begin{bmatrix} r_{1} \\ r_{2} \\ \vdots \\ r_{q} \end{bmatrix}$$

$$H_{1}: R\beta \neq r \implies \begin{bmatrix} r_{10}\beta_{0} + r_{11}\beta_{1} + r_{12}\beta_{2} + \dots + r_{qk}\beta_{k} \end{bmatrix} = \begin{bmatrix} r_{1} \\ r_{2} \\ \vdots \\ r_{q} \end{bmatrix}$$

Some Specific Examples

Consider the linear regression model given by the PRE

$$Y_{i} = \beta_{0} + \beta_{1}X_{i1} + \beta_{2}X_{i2} + \beta_{3}X_{i3} + \beta_{4}X_{i4} + u_{i} \qquad (i = 1, ..., N)$$
(4)

Test 1

The null and alternative hypotheses are:

• The restrictions matrix R in this case is the 1×5 row vector:

 $\mathbf{R} = \begin{bmatrix} 0 & 0 & 1 & 0 & 0 \end{bmatrix}.$

• The restrictions vector r is in this case the scalar 0 since there is only one restriction specified by the null hypothesis H₀:

 $\mathbf{r} = \mathbf{0}.$

• The matrix-vector product $R\beta$ in this case is:

$$R\beta = \begin{bmatrix} 0 & 0 & 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} \beta_0 \\ \beta_1 \\ \beta_2 \\ \beta_3 \\ \beta_4 \end{bmatrix} = 0\beta_0 + 0\beta_1 + 1\beta_2 + 0\beta_3 + 0\beta_4 = \beta_2$$

• The null hypothesis H_0 : $R\beta = r$ is therefore the single equation:

$$H_0: \quad \beta_2 = 0$$

Test 2

The PRE is again

$$Y_{i} = \beta_{0} + \beta_{1}X_{i1} + \beta_{2}X_{i2} + \beta_{3}X_{i3} + \beta_{4}X_{i4} + u_{i} \qquad (i = 1, ..., N)$$
(4)

The null and alternative hypotheses are:

- $\begin{array}{ll} H_0: & \beta_1=0 \ \ \text{and} \ \ \beta_2=0 & \ \ \text{two linear restrictions on coefficient vector } \beta \\ H_1: & \beta_1\neq 0 \ \ \text{and/or} \ \ \beta_2\neq 0 & \end{array}$
- The restrictions matrix R in this case is the 2×5 row vector:

$$\mathbf{R} = \begin{bmatrix} 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \end{bmatrix}$$

• The restrictions vector r is in this case the 2×1 column vector of zeros:

$$\mathbf{r} = \begin{bmatrix} \mathbf{0} \\ \mathbf{0} \end{bmatrix}$$

• The matrix-vector product $R\beta$ in this case is:

$$R\beta = \begin{bmatrix} 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} \beta_0 \\ \beta_1 \\ \beta_2 \\ \beta_3 \\ \beta_4 \end{bmatrix} = \begin{bmatrix} 0\beta_0 + 1\beta_1 + 0\beta_2 + 0\beta_3 + 0\beta_4 \\ 0\beta_0 + 0\beta_1 + 1\beta_2 + 0\beta_3 + 0\beta_4 \end{bmatrix} = \begin{bmatrix} \beta_1 \\ \beta_2 \end{bmatrix}$$

• The null hypothesis H_0 : $R\beta = r$ is therefore the matrix equation:

H₀:
$$\begin{bmatrix} \beta_1 \\ \beta_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$
 which says " $\beta_1 = 0$ and $\beta_2 = 0$ "

Test 3

The PRE is again

$$Y_{i} = \beta_{0} + \beta_{1}X_{i1} + \beta_{2}X_{i2} + \beta_{3}X_{i3} + \beta_{4}X_{i4} + u_{i} \qquad (i = 1, ..., N)$$
(4)

The null and alternative hypotheses are:

- $\begin{array}{lll} H_0: & \beta_1 = \beta_3 \ \text{and} \ \beta_2 = \ \beta_4 & or & \beta_1 \beta_3 = 0 \ \text{and} \ \beta_2 + \beta_4 = 0 & (q = 2) \\ \\ H_1: & \beta_1 \neq \beta_3 \ \text{and/or} \ \beta_2 \neq \beta_4 & or & \beta_1 \beta_3 \neq 0 \ \text{and/or} \ \beta_2 + \beta_4 \neq 0 \end{array}$
- The restrictions matrix R in this case is the 2×5 row vector:

$$\mathbf{R} = \begin{bmatrix} 0 & 1 & 0 & -1 & 0 \\ 0 & 0 & 1 & 0 & 1 \end{bmatrix}$$

• The restrictions vector r is in this case the 2×1 column vector of zeros:

$$\mathbf{r} = \begin{bmatrix} 0\\ 0 \end{bmatrix}$$

• The matrix-vector product $R\beta$ in this case is:

$$\mathbf{R}\boldsymbol{\beta} = \begin{bmatrix} 0 & 1 & 0 & -1 & 0 \\ 0 & 0 & 1 & 0 & 1 \end{bmatrix} \begin{bmatrix} \beta_0 \\ \beta_1 \\ \beta_2 \\ \beta_3 \\ \beta_4 \end{bmatrix} = \begin{bmatrix} 0\beta_0 + 1\beta_1 + 0\beta_2 - 1\beta_3 + 0\beta_4 \\ 0\beta_0 + 0\beta_1 + 1\beta_2 + 0\beta_3 + 1\beta_4 \end{bmatrix} = \begin{bmatrix} \beta_1 - \beta_3 \\ \beta_2 + \beta_4 \end{bmatrix}$$

• The null hypothesis H_0 : $R\beta = r$ is therefore the matrix equation:

H₀:
$$\begin{bmatrix} \beta_1 - \beta_3 \\ \beta_2 + \beta_4 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$
 which says " $\beta_1 - \beta_3 = 0$ and $\beta_2 + \beta_4 = 0$ "

Test 4

The PRE is again

$$Y_{i} = \beta_{0} + \beta_{1}X_{i1} + \beta_{2}X_{i2} + \beta_{3}X_{i3} + \beta_{4}X_{i4} + u_{i} \qquad (i = 1, ..., N)$$
(4)

The null and alternative hypotheses are:

- $$\begin{split} H_0: \quad \beta_1 + 2\beta_2 &= \beta_3 + 2\beta_4 \quad or \quad \beta_1 + 2\beta_2 \beta_3 2\beta_4 = 0 \qquad (q = 1) \\ H_1: \quad \beta_1 + 2\beta_2 \neq \beta_3 + 2\beta_4 \quad or \quad \beta_1 + 2\beta_2 \beta_3 2\beta_4 \neq 0 \end{split}$$
- The restrictions matrix R in this case is the 1×5 row vector:

$$\mathbf{R} = \begin{bmatrix} 0 & 1 & 2 & -1 & -2 \end{bmatrix}$$

• The restrictions vector r is in this case the 1×1 scalar 0:

$$\mathbf{r} = \mathbf{0}$$

• The matrix-vector product $R\beta$ in this case is the 1×1 scalar:

$$\mathbf{R}\boldsymbol{\beta} = \begin{bmatrix} 0 & 1 & 2 & -1 & -2 \end{bmatrix} \begin{bmatrix} \beta_0 \\ \beta_1 \\ \beta_2 \\ \beta_3 \\ \beta_4 \end{bmatrix} = \begin{bmatrix} 0\beta_0 + 1\beta_1 + 2\beta_2 - 1\beta_3 - 2\beta_4 \end{bmatrix}$$
$$= \beta_1 + 2\beta_2 - \beta_3 - 2\beta_4$$

• The null hypothesis H_0 : $R\beta = r$ is therefore the equation:

$$\mathbf{H}_0: \quad \boldsymbol{\beta}_1 + 2\boldsymbol{\beta}_2 - \boldsymbol{\beta}_3 - 2\boldsymbol{\beta}_4 = \mathbf{0}$$

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3. The Three Principles of Hypothesis Testing

- Given the null hypothesis H_0 : $R\beta r = 0$ and the alternative hypothesis H_1 : $R\beta - r \neq 0$, there are **two alternative sets of parameter estimates** of the PRE $y = X\beta + u$ that one might use to compute a test statistic.
 - 1. The *restricted* parameter estimates computed under H₀: $R\beta r = 0$, which are denoted as follows:
 - $\tilde{\beta}$ = the *restricted* OLS estimator of β ;

 $\widetilde{u} = y - X\widetilde{\beta}$ = the *restricted* OLS residual vector;

$$RSS_0 = RSS_R = RSS(\widetilde{\beta}) = \widetilde{u}^T \widetilde{u} = \sum_{i=1}^N \widetilde{u}_i^2$$

= the *restricted* residual sum of squares;

 $df_0 = N - (K - q) = N - K + q$ = the degrees of freedom for RSS₀;

 $\tilde{\sigma}^2 = RSS_0/df_0 = RSS_0/N - (K - q)$ = the *restricted* OLS estimator of σ^2 ;

 $R_{R}^{2} = ESS_{0}/TSS = 1 - (RSS_{0}/TSS) = \text{the restricted } R$ -squared.

2. The *unrestricted* parameter estimates computed under H₁: $R\beta - r \neq \underline{0}$, which are denoted as follows:

 $\hat{\beta}$ = the *unrestricted* OLS estimator of β ;

 $\hat{u} = y - X\hat{\beta}$ = the *unrestricted* residual vector;

$$\mathbf{RSS}_{1} = \mathbf{RSS}_{U} = \mathbf{RSS}(\hat{\beta}) = \hat{\mathbf{u}}^{\mathrm{T}}\hat{\mathbf{u}} = \sum_{i=1}^{\mathrm{N}} \hat{\mathbf{u}}_{i}^{2}$$

= the *unrestricted* residual sum of squares;

 $df_1 = N - K$ = the degrees of freedom for RSS₁;

 $\hat{\sigma}^2 = RSS_1/N - K$ = the *unrestricted* OLS estimator of σ^2 .

 $R_{\rm U}^2 = ESS_1/TSS = 1 - (RSS_1/TSS) =$ the *unrestricted* R-squared.

- The computation of hypothesis tests of linear coefficient restrictions can be performed in general in three different ways:
 - 1. using *only* the *unrestricted* parameter estimates of the model;
 - 2. using *only* the *restricted* parameter estimates of the model;
 - **3.** using *both* the *restricted* and *unrestricted* parameter estimates of the model.
- These three options correspond to the **three fundamental principles of hypothesis testing**.
 - 1. The Wald principle of hypothesis testing computes hypothesis tests using *only* the *unrestricted* parameter estimates of the model computed under the alternative hypothesis H₁.
 - 2. The Lagrange Multiplier (LM) principle of hypothesis testing computes hypothesis tests using *only* the *restricted* parameter estimates of the model computed under the null hypothesis H₀.
 - **3.** The **Likelihood Ratio** (**LR**) **principle** of hypothesis testing computes hypothesis tests using *both* the *restricted* **parameter estimates** of the model computed under the null hypothesis H₀ *and* the *unrestricted* **parameter estimates** of the model computed under the alternative hypothesis H₁.

4. Likelihood Ratio F-Tests of Linear Coefficient Restrictions

□ Null and Alternative Hypotheses

• The **null hypothesis** is that the regression coefficient vector β satisfies a set of q independent linear coefficient restrictions:

H₀: $R\beta = r \iff R\beta - r = 0$

• The **alternative hypothesis** is that the regression coefficient vector β does not satisfy the set of q independent linear coefficient restrictions specified by H₀:

$$H_1: \quad R\beta \neq r \quad \Leftrightarrow \quad R\beta - r \neq \underline{0}$$

D The Likelihood Ratio F-Statistic

The LR F-statistic can be written in either of two equivalent forms.

1. <u>Form 1 of the LR F-statistic</u> is expressed in terms of the restricted and unrestricted residual sums of squares, RSS₀ and RSS₁:

$$F_{LR} = \frac{(RSS_0 - RSS_1)/(df_0 - df_1)}{RSS_1/df_1} = \frac{(RSS_0 - RSS_1)}{RSS_1} \frac{df_1}{(df_0 - df_1)}$$
(F1)

$$F_{LR} = \frac{(RSS_0 - RSS_1)/q}{RSS_1/(N - K)} = \frac{(RSS_0 - RSS_1)}{RSS_1} \frac{(N - K)}{q}$$
(F1)

where:

 $RSS_0 =$ the *residual sum of squares* for the <u>restricted</u> OLS-SRE; $df_0 = N - K_0 =$ the *degrees of freedom* for RSS_0 , the <u>restricted</u> RSS; $K_0 = K - q =$ the *number of free regression coefficients* in the <u>restricted</u> model;

 $RSS_1 =$ the *residual sum of squares* for the <u>unrestricted</u> OLS-SRE; $df_1 = N - K =$ the *degrees of freedom* for RSS_1 , the <u>unrestricted</u> RSS; K = k + 1 =the *number of free regression coefficients* in the <u>unrestricted</u> model;

 $q = df_0 - df_1 = K - K_0 =$ the **number of** *independent linear coefficient restrictions* specified by the null hypothesis H₀.

Note: The value of q is calculated as follows:

$$q = df_0 - df_1 = N - K_0 - (N - K) = N - K_0 - N + K = K - K_0.$$

2. Form 2 of the LR F-statistic is expressed in terms of the restricted and unrestricted R-squared values, R_R^2 and R_U^2 :

$$\mathbf{F} = \frac{(\mathbf{R}_{\mathrm{U}}^{2} - \mathbf{R}_{\mathrm{R}}^{2})/(df_{0} - df_{1})}{(1 - \mathbf{R}_{\mathrm{U}}^{2})/df_{1}} = \frac{(\mathbf{R}_{\mathrm{U}}^{2} - \mathbf{R}_{\mathrm{R}}^{2})}{(1 - \mathbf{R}_{\mathrm{U}}^{2})} \frac{df_{1}}{(df_{0} - df_{1})}$$
(F2)

$$F = \frac{(R_{\rm U}^2 - R_{\rm R}^2)/q}{(1 - R_{\rm U}^2)/(N - K)} = \frac{(R_{\rm U}^2 - R_{\rm R}^2)}{(1 - R_{\rm U}^2)} \frac{(N - K)}{q}$$
(F2)

where:

$$R_{R}^{2} = \text{the } \textbf{R-squared value} \text{ for the } \underline{restricted} \text{ OLS-SRE};$$

$$K_{0} = K - q = \text{the } number of free regression coefficients in the } \underline{restricted} \\ \textbf{model};$$

$$df_{0} = N - K_{0} = N - (K - q) = N - K + q = \text{the } degrees of freedom \text{ for } \textbf{RSS}_{0}, \\ \text{the } \underline{restricted} \\ \textbf{RSS};$$

$$R_{U}^{2} = \text{the } \textbf{R-squared value} \text{ for the } \underline{unrestricted} \\ \textbf{OLS-SRE};$$

$$K = k + 1 = \text{the } number of free regression coefficients in the } \underline{unrestricted} \\ \textbf{model};$$

$$df_{1} = N - K = \text{the } degrees of freedom \text{ for } \textbf{RSS}_{1}, \text{ the } \underline{unrestricted} \\ \textbf{RSS};$$

$$q = df_{0} - df_{1} = K - K_{0} = \text{ the number } of \text{ independent linear coefficient} \\ \textbf{H}_{0}.$$

□ Null distribution of the LR F-statistic

Under error normality assumption A6, the LR F-statistic F_{LR} is distributed under H₀ (i.e., assuming the null hypothesis H₀ is true) as F[q, N–K], the F distribution with q numerator degrees of freedom and N–K denominator degrees of freedom:

 $F_{LR} \sim F[q, N - K]$ under $H_0: R\beta = r$.

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Computation of the LR F-statistic

Computation of the LR F-statistic requires estimation of both the restricted and unrestricted models.

• The *restricted* OLS-SRE estimated under the null hypothesis

 $H_0: \quad R\beta = r \quad \Longleftrightarrow \quad R\beta - r = \underline{0}$

The regression coefficient vector $\boldsymbol{\beta}$ satisfies q independent linear coefficient restrictions

is written in matrix form as

$$y = X\widetilde{\beta} + \widetilde{u} = \widetilde{y} + \widetilde{u}$$
⁽⁵⁾

or in scalar form as

$$Y_{i} = \widetilde{\beta}_{0} + \widetilde{\beta}_{1}X_{i1} + \widetilde{\beta}_{2}X_{i2} + \dots + \widetilde{\beta}_{k}X_{ik} + \widetilde{u}_{i} = \widetilde{Y}_{i} + \widetilde{u}_{i} \qquad (i = 1, ..., N)$$

where:

- $\tilde{\beta}$ is the *restricted* **OLS estimator** of the coefficient vector β with typical element $\tilde{\beta}_{j}$ (j = 0, ..., k), the *restricted* **OLS estimate of** β_{j} ;
- $\tilde{y} = X\tilde{\beta}$ is the *restricted* **OLS prediction vector** with typical element \tilde{Y}_i (i = 1, ..., N), the *restricted* **predicted value** of the dependent variable Y for observation i, where

$$\widetilde{\boldsymbol{Y}}_{i} = \widetilde{\boldsymbol{\beta}}_{0} + \widetilde{\boldsymbol{\beta}}_{1}\boldsymbol{X}_{i1} + \widetilde{\boldsymbol{\beta}}_{2}\boldsymbol{X}_{i2} + \dots + \widetilde{\boldsymbol{\beta}}_{k}\boldsymbol{X}_{ik} \qquad (i = 1, \, ..., \, N)$$

• $\tilde{u} = y - \tilde{y} = y - X\tilde{\beta}$ is the *restricted* **OLS residual vector** with typical element \tilde{u}_i (i = 1, ..., N), the *restricted* **OLS residual** for observation i, where

$$\widetilde{u}_{i} = Y_{i} - \widetilde{Y}_{i} = Y_{i} - \widetilde{\beta}_{0} - \widetilde{\beta}_{1}X_{i1} - \widetilde{\beta}_{2}X_{i2} - \dots - \widetilde{\beta}_{k}X_{ik} \quad (i = 1, ..., N)$$

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• the OLS decomposition equation for the restricted OLS-SRE is

$$TSS = ESS_0 + RSS_0$$
(5.1)

where

$$TSS = y^{T}y - N\overline{Y}^{2} = \sum_{i=1}^{N} (Y_{i} - \overline{Y})^{2} = \sum_{i=1}^{N} Y_{i}^{2} - N\overline{Y}^{2}$$
 has $df = N - 1$

$$ESS_{0} = \widetilde{y}^{T}\widetilde{y} - N\overline{Y}^{2} = \sum_{i=1}^{N} (\widetilde{Y}_{i} - \overline{Y})^{2} = \sum_{i=1}^{N} \widetilde{Y}_{i}^{2} - N\overline{Y}^{2}$$
 has $df = K_{0} - 1 - q$

$$RSS_{0} = \widetilde{u}^{T}\widetilde{u} = \sum_{i=1}^{N} \widetilde{u}_{i}^{2}$$
 has $df_{0} = N - (K_{0} - q) = N - K_{0} + q$

• the *restricted* **R-squared** for the *restricted* **OLS-SRE** is

$$R_{R}^{2} = \frac{ESS_{0}}{TSS} = 1 - \frac{RSS_{0}}{TSS}.$$
 (5.2)

• The *unrestricted* OLS-SRE estimated under the alternative hypothesis

H₁:
$$R\beta \neq r \iff R\beta - r \neq \underline{0}$$

The regression coefficient vector β does not satisfy the q independent linear coefficient restrictions specified by H₀

is written in matrix form as

$$\mathbf{y} = \mathbf{X}\hat{\boldsymbol{\beta}} + \hat{\mathbf{u}} = \hat{\mathbf{y}} + \hat{\mathbf{u}} \tag{6}$$

or in scalar form as

$$Y_{i} = \hat{\beta}_{0} + \hat{\beta}_{1}X_{i1} + \hat{\beta}_{2}X_{i2} + \dots + \hat{\beta}_{k}X_{ik} + \hat{u}_{i} = \hat{Y}_{i} + \hat{u}_{i} \qquad (i = 1, ..., N)$$

where:

• $\hat{\beta}$ is the *unrestricted* **OLS estimator** of the coefficient vector β with typical element $\hat{\beta}_{j}$ (j = 0, ..., k), the *unrestricted* **OLS estimate of** β_{j} ;

• $\hat{y} = X\hat{\beta}$ is the *unrestricted* **OLS prediction vector** with typical element \hat{Y}_i (i = 1, ..., N), the *unrestricted* **predicted value** of the dependent variable Y for observation i, where

$$\hat{\mathbf{Y}}_{i} = \hat{\beta}_{0} + \hat{\beta}_{1} \mathbf{X}_{i1} + \hat{\beta}_{2} \mathbf{X}_{i2} + \dots + \hat{\beta}_{k} \mathbf{X}_{ik} \qquad (i = 1, ..., N)$$

• $\hat{u} = y - \hat{y} = y - X\hat{\beta}$ is the *unrestricted* OLS residual vector with typical element \hat{u}_i (i = 1, ..., N), the *unrestricted* OLS residual for observation i, where

$$\hat{u}_{i} = Y_{i} - \hat{Y}_{i} = Y_{i} - \hat{\beta}_{0} - \hat{\beta}_{1}X_{i1} - \hat{\beta}_{2}X_{i2} - \dots - \hat{\beta}_{k}X_{ik}$$
 (i = 1, ..., N)

• the OLS decomposition equation for the unrestricted OLS-SRE is

$$TSS = ESS_1 + RSS_1 \tag{6.1}$$

where

$$TSS = y^{T}y - N\overline{Y}^{2} = \sum_{i=1}^{N} (Y_{i} - \overline{Y})^{2} = \sum_{i=1}^{N} Y_{i}^{2} - N\overline{Y}^{2}$$
 has df = N - 1

$$ESS_{1} = \hat{y}^{T}\hat{y} - N\overline{Y}^{2} = \sum_{i=1}^{N} (\hat{Y}_{i} - \overline{Y})^{2} = \sum_{i=1}^{N} \hat{Y}_{i}^{2} - N\overline{Y}^{2}$$
 has df = K - 1

$$RSS_{1} = \hat{u}^{T}\hat{u} = \sum_{i=1}^{N} \hat{u}_{i}^{2}$$
 has df_{1} = N - K

• the unrestricted R-squared for the unrestricted OLS-SRE is

$$R_{\rm U}^2 = \frac{{\rm ESS}_1}{{\rm TSS}} = 1 - \frac{{\rm RSS}_1}{{\rm TSS}}.$$
 (6.2)

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• Compare the OLS decomposition equations for the <u>restricted</u> and <u>unrestricted</u> OLS-SREs.

$TSS = ESS_0 + RSS_0.$	[for <u>restricted</u> SRE]	(5.1)
$TSS = ESS_1 + RSS_1.$	[for <i>unrestricted</i> SRE]	(6.1)

• Since the Total Sum of Squares (TSS) is the same for both decompositions, it follows that

$$\mathbf{ESS}_0 + \mathbf{RSS}_0 = \mathbf{ESS}_1 + \mathbf{RSS}_1. \tag{7}$$

• Subtracting first RSS₁ and then ESS₀ from both sides of equation (9) allows equation (9) to be written as:

$$RSS_0 - RSS_1 = ESS_1 - ESS_0$$
(8)

where

$RSS_0 - RSS_1 =$	the <i>increase</i> in RSS attributable to <i>imposing</i> the restrictions specified by the null hypothesis H ₀ ;
$ESS_1 - ESS_0 =$	the <i>increase</i> in ESS attributable to <i>relaxing</i> the restrictions specified by the null hypothesis H ₀ .

<u>Result</u>: Imposing one or more linear coefficient restrictions on the regression coefficients β_j (j = 0, ..., k) always *increases* (or leaves unchanged) the *residual* sum of squares, and hence always *reduces* (or leaves unchanged) the *explained* sum of squares. Consequently,

 $RSS_0 \ge RSS_1 \iff ESS_1 \ge ESS_0$

so that

 $RSS_0 - RSS_1 \ge 0 \quad \Leftrightarrow \quad ESS_1 - ESS_0 \ge 0.$

In other words, both sides of equation (8) are always non-negative.

5. Wald F-Tests of Linear Coefficient Restrictions

□ The Wald F-Test is Based on the Wald Principle of Hypothesis Testing

The **Wald principle** of hypothesis testing computes hypothesis tests using *only* **the** *unrestricted* **parameter estimates** of the model computed under the alternative hypothesis H₁: $R\beta \neq r$. These unrestricted parameter estimates can be denoted as $\hat{\theta} = (\hat{\beta}, \hat{\sigma}^2)$.

□ General Wald F-statistic. The general Wald F-statistic is obtained by simply dividing the general Wald statistic W in (10) by q, the number of independent linear coefficient restrictions specified by the null hypothesis H_0 : $R\beta = r$:

$$F_{WALD} = \frac{1}{q}W = \frac{\left(R\hat{\beta} - r\right)^{T}\left(R\hat{V}_{\hat{\beta}}R^{T}\right)^{-1}\left(R\hat{\beta} - r\right)}{q}$$
(9)

where:

$$W = \text{the general Wald statistic given below;}$$

$$\hat{\beta} = a \text{ consistent unrestricted estimator of } \beta, \text{ such as the OLS estimator;}$$

$$\hat{V}_{\hat{\beta}} = a \text{ consistent estimator of } V_{\hat{\beta}}.$$

The *general Wald test statistic* W for testing the null hypothesis H_0 : $R\beta = r$ against the alternative hypothesis H_1 : $R\beta \neq r$ takes the form

$$W = \left(R\hat{\beta} - r\right)^{T} \left(R\hat{V}_{\hat{\beta}}R^{T}\right)^{-1} \left(R\hat{\beta} - r\right)^{a} \chi^{2}[q] \text{ under } H_{0}$$
(10)

where

$$\hat{\beta} = a$$
 consistent unrestricted estimator of β , such as the OLS estimator;
 $\hat{V}_{\hat{\beta}} = a$ *consistent* estimator of $V_{\hat{\beta}}$;
 $\chi^{2}[q] =$ the chi-square distribution with q degrees of freedom.

Notes: Both the coefficient estimator $\hat{\beta}$ and the coefficient covariance matrix estimator $\hat{V}_{\hat{\beta}}$ used in the general Wald statistic W must be *consistent*, and are computed using only *unrestricted* estimates of the linear regression model under the alternative hypothesis H₁: R $\beta \neq r$.

• Null distribution of Wald-F Statistic: With the error normality assumption A6, the null distribution of the general Wald-F statistic -- that is, the distribution of the Wald-F statistic if the null hypothesis H_0 is true -- is F[q, N – K], the central F distribution with q numerator degrees of freedom and N–K denominator degrees of freedom.

The short way of saying this is:

$$F_{WALD} = \frac{1}{q} W \sim F[q, N - K] \quad \text{under } H_0: R\beta = r$$
(11)

where

F[q, N-K] = the F-distribution with q numerator degrees of freedom and N-K denominator degrees of freedom.

Notes:

- 1. The null distribution of the F_{WALD} statistic is exactly F[q, N-K] only if the error normality assumption A6 is true.
- 2. However, even if the normality assumption A6 is not true, the null distribution of the F_{WALD} statistic is still approximately F[q, N–K] under fairly general conditions.

□ <u>Common Form of the Wald F-statistic</u>. In practice, the most common form of the Wald F-statistic is that obtained by using the OLS coefficient covariance matrix estimator in place of $\hat{V}_{\hat{\beta}}$ in (9) and (10):

$$F_{W} = \frac{1}{q} W_{OLS} = \frac{\left(R\hat{\beta} - r\right)^{T} \left(R\hat{V}_{OLS}R^{T}\right)^{-1} \left(R\hat{\beta} - r\right)}{q}$$
(12)

where

- $\hat{V}_{OLS}(\hat{\beta}) = \hat{V}_{OLS} = \hat{\sigma}^2 (X^T X)^{-1} = \text{ the OLS estimator of } V_{\hat{\beta}};$ $\hat{\sigma}^2 = \frac{RSS_1}{N-K} = \frac{\hat{u}^T \hat{u}}{N-K} = \frac{\sum_{i=1}^N \hat{u}_i^2}{N-K} = \text{ the unrestricted OLS estimator of } \sigma^2;$ $W_{OLS} = (R\hat{\beta} r)^T (R\hat{V}_{OLS} R^T)^{-1} (R\hat{\beta} r) \stackrel{a}{\sim} \chi^2[q] \text{ under } H_0.$
- Null distribution of the F_w Statistic: With the error normality assumption A6, the null distribution of the F_w statistic (12) that is, the distribution of the Wald-F statistic if the null hypothesis H₀ is true is F[q, N K], the central F distribution with q numerator degrees of freedom and N–K denominator degrees of freedom.

The short way of saying this is:

$$F_{W} = \frac{1}{q} W_{OLS} \sim F[q, N-K] \quad \text{under } H_0: R\beta = r$$
(13)

where

F[q, N-K] = the F-distribution with q numerator degrees of freedom and N-K denominator degrees of freedom.

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- Notes on Computation of $\mathbf{F}_{\mathbf{W}}$
- The Wald F-statistic F_W in (12) is computed using only the *unrestricted* **OLS** coefficient estimates $\hat{\beta}$ and the OLS estimate \hat{V}_{OLS} of the variance-covariance matrix of $\hat{\beta}$.
- Both the *unrestricted* OLS coefficient estimator $\hat{\beta}$ and the OLS covariance matrix estimator \hat{V}_{OLS} are *unbiased* and *consistent* under the assumptions of the classical linear regression model.

6. Relationship Between Wald and LR F-Tests

D The Wald and LR F-Statistics

$$F_{W} = \frac{1}{q} W_{OLS} = \frac{(R\hat{\beta} - r)^{T} (R\hat{V}_{OLS} R^{T})^{-1} (R\hat{\beta} - r)}{q} \sim F[q, N - K] \text{ under } H_{0}$$

$$F_{LR} = \frac{(RSS_{0} - RSS_{1})/q}{RSS_{1}/(N - K)} = \frac{(RSS_{0} - RSS_{1})}{RSS_{1}} \frac{(N - K)}{q} \sim F[q, N - K] \text{ under } H_{0}$$

□ Key Result

The key to understanding the relationship between the Wald F-statistic F_w and the LR F-statistic F_{LR} is the following important result (given without the tedious proof):

The quadratic form $\Phi(\hat{\beta})$ defined as

$$\Phi(\hat{\beta}) = \left(R\hat{\beta} - r\right)^{T} \left(R\left(X^{T}X\right)^{-1}R^{T}\right)^{-1} \left(R\hat{\beta} - r\right)$$

can be shown to equal the difference between the restricted and unrestricted residual sums of squares

$$\mathbf{RSS}_0 - \mathbf{RSS}_1 = \widetilde{\mathbf{u}}^{\mathrm{T}} \widetilde{\mathbf{u}} - \widehat{\mathbf{u}}^{\mathrm{T}} \widehat{\mathbf{u}} \ .$$

That is,

$$\Phi(\hat{\beta}) = \left(R\hat{\beta} - r\right)^{T} \left(R\left(X^{T}X\right)^{-1}R^{T}\right)^{-1} \left(R\hat{\beta} - r\right) = \tilde{\mathbf{u}}^{T}\tilde{\mathbf{u}} - \hat{\mathbf{u}}^{T}\hat{\mathbf{u}} = RSS_{0} - RSS_{1}.$$
 (14)

\Box Rewrite the F_W Statistic

- Use the result (14) and the formula for $\hat{\sigma}_{OLS}^2$ to rewrite the Wald F-statistic F_W .
- **1.** Rewrite the Wald F-statistic F_W as follows

Substitute for $\,\hat{V}_{OLS}\,$ in the formula for F_W the expression

$$\hat{\mathbf{V}}_{\text{OLS}} = \hat{\sigma}^2 \left(\mathbf{X}^{\text{T}} \mathbf{X} \right)^{-1}$$

This gives

$$\begin{split} F_{W} &= \frac{\left(R\hat{\beta} - r\right)^{T} \left(R\hat{V}_{OLS} R^{T}\right)^{-1} \left(R\hat{\beta} - r\right)}{q} \\ &= \frac{\left(R\hat{\beta} - r\right)^{T} \left(R\hat{\sigma}_{OLS}^{2} (X^{T}X)^{-1}R^{T}\right)^{-1} \left(R\hat{\beta} - r\right)}{q} \\ &= \frac{\left(R\hat{\beta} - r\right)^{T} \left(\hat{\sigma}_{OLS}^{2} R (X^{T}X)^{-1}R^{T}\right)^{-1} \left(R\hat{\beta} - r\right)}{q} \\ &= \frac{\left(R\hat{\beta} - r\right)^{T} \left(R (X^{T}X)^{-1}R^{T}\right)^{-1} \left(R\hat{\beta} - r\right)}{q\hat{\sigma}_{OLS}^{2}} \\ &= \frac{\left(R\hat{\beta} - r\right)^{T} \left(R (X^{T}X)^{-1}R^{T}\right)^{-1} \left(R\hat{\beta} - r\right)}{\hat{\sigma}_{OLS}^{2}}. \end{split}$$
(15)

2. Now substitute for $\hat{\sigma}_{OLS}^2$ in the last line of (15) the expression

$$\hat{\sigma}_{OLS}^2 = \frac{RSS_1}{N-K} = \frac{\hat{u}^T\hat{u}}{N-K}.$$

This allows us to rewrite the F_W statistic as

$$\begin{split} F_{\rm W} &= \frac{\left(R\hat{\beta} - r\right)^{\rm T} \left(R(X^{\rm T}X)^{-1}R^{\rm T}\right)^{-1} \left(R\hat{\beta} - r\right) / q}{\hat{\sigma}_{\rm OLS}^2} \\ &= \frac{\left(R\hat{\beta} - r\right)^{\rm T} \left(R(X^{\rm T}X)^{-1}R^{\rm T}\right)^{-1} \left(R\hat{\beta} - r\right) / q}{\hat{u}^{\rm T}\hat{u} / (N - K)}. \end{split}$$

3. Finally, use result (14) above to replace the quadratic form in the numerator of F_W , namely $(R\hat{\beta} - r)^T (R(X^TX)^{-1}R^T)^{-1}(R\hat{\beta} - r)$, with the equivalent difference between the restricted residual sum of squares $\tilde{u}^T\tilde{u}$ and the unrestricted residual sum of squares $\tilde{u}^T\hat{u}$. This permits the F_W statistic to be written as:

$$F_{W} = \frac{(R\hat{\beta} - r)^{T} (R(X^{T}X)^{-1}R^{T})^{-1} (R\hat{\beta} - r)/q}{\hat{u}^{T}\hat{u}/(N - K)}$$

$$= \frac{(\tilde{u}^{T}\tilde{u} - \hat{u}^{T}\hat{u})/q}{\hat{u}^{T}\hat{u}/(N - K)}$$

$$= \frac{(RSS_{0} - RSS_{1})/q}{RSS_{1}/(N - K)}$$
(16.1)

where $RSS_0 = \tilde{u}^T \tilde{u}$ = the restricted residual sum of squares and $RSS_1 = \hat{u}^T \hat{u}$ = the unrestricted residual sum of squares.

• <u>**Result</u>**: The Wald F-statistic F_W can be written in terms of the restricted and unrestricted residual sums of squares as</u>

$$F_{W} = \frac{\left(R\hat{\beta} - r\right)^{T} \left(R\hat{V}_{OLS}R^{T}\right)^{-1} \left(R\hat{\beta} - r\right)}{q} = \frac{\left(RSS_{0} - RSS_{1}\right)/q}{RSS_{1}/(N - K)}.$$
(17)

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\Box The F_W and F_{LR} Statistics are Equal

$$F_{W} = \frac{\left(R\hat{\beta} - r\right)^{T} \left(R\hat{V}_{OLS} R^{T}\right)^{-1} \left(R\hat{\beta} - r\right)}{q} = \frac{\left(RSS_{0} - RSS_{1}\right)/q}{RSS_{1}/(N-K)} = F_{LR}.$$

□ Tests Based on the F_W and F_{LR} Statistics are Equivalent

The Wald F-statistic F_W and the LR F-statistic F_{LR} yield equivalent or identical tests of H_0 : $R\beta = r$ against H_1 : $R\beta \neq r$.

This equivalence follows from two facts:

1. The two test statistics F_W and F_{LR} are *equal*; that is, they yield identical calculated sample values of the F-statistic.

 $F_W = F_{LR}$

2. The two test statistics F_W and F_{LR} have *identical null distributions*, namely the F[q, N–K] distribution.

 $F_W \sim F[q, N-K]$ under $H_0: R\beta = r$

and

 $F_{LR} \sim F[q, N-K]$ under $H_0: R\beta = r$.

• <u>Result</u>:

$$F_W = F_{LR} \sim F[q, N - K]$$
 under $H_0: R\beta = r.$